# Superconvergence of the Local Discontinuous Galerkin Method for One Dimensional Nonlinear Convection-Diffusion Equations 

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#### Abstract

In this paper, we study superconvergence properties of the local discontinuous Galerkin (LDG) methods for solving nonlinear convection-diffusion equations in one space dimension. The main technicality is an elaborate estimate to terms involving projection errors. By introducing a new projection and constructing some correction functions, we prove the $(2 k+1)$ th order superconvergence for the cell averages and the numerical flux in the discrete $L^{2}$ norm with polynomials of degree $k \geq 1$, no matter whether the flow direction $f^{\prime}(u)$ changes or not. Superconvergence of order $k+2(k+1)$ is obtained for the LDG error (its derivative) at interior right (left) Radau points, and the convergence order for the error derivative at Radau points can be improved to $k+2$ when the direction of the flow doesn't change. Finally, a supercloseness result of order $k+2$ towards a special Gauss-Radau projection of the exact solution is shown. The superconvergence analysis can be extended to the generalized numerical fluxes and the mixed boundary conditions. All theoretical findings are confirmed by numerical experiments.


Keywords Local discontinuous Galerkin method • Nonlinear convection-diffusion equation • Superconvergence • Correction function • Projection

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## 1 Introduction

In this paper, we investigate superconvergence of the local discontinuous Galerkin (LDG) method for one-dimensional nonlinear convection-diffusion equations

$$
\left.\begin{array}{rl}
u_{t}+f(u)_{x}-b u_{x x} & =g(x, t), \\
u(x, 0) & =u_{0}(x), \tag{1.1b}
\end{array} \quad x \in[0,2 \pi], ~ l 0,2 \pi\right] \times(0, T],
$$

where $b>0$ is a constant, $u_{0}$ is smooth, and $g$ is a smooth function. We assume that the nonlinear flux function $f(u)$ is sufficiently smooth with respect to the variable $u$, and the exact solution is assumed to be smooth on $[0,2 \pi] \times[0, T]$ for a fixed $T$. The main task in deriving superconvergence is a delicate treatment for terms involving projection errors. By defining a new projection and constructing some correction functions, superconvergence properties for Radau points, cell averages and supercloseness are shown. Both the periodic boundary condition and mixed boundary conditions are considered.

As a class of efficient methods for solving partial differential equations (PDEs) involving high order spatial derivatives, the LDG method was proposed by [17] for convection-diffusion equations. Typically, an auxiliary variable will be introduced so that the standard discontinuous Galerkin (DG) methods can be applied to the resulting first-order system. Due to its numerical stability and local solvability of auxiliary variables, the LDG method has been widely used for solving a series of high order equations; see, e.g., [9,15].

In addition to optimal error estimates of LDG methods, the research of superconvergence has been a hot topic in recent years. Superconvergence results for Radau points have been obtained by using the Fourier approach [18] and the finite element technique $[8,10,14]$ for different types of PDEs. Suboptimal supercloseness results of order $k+3 / 2$ (with $k$ being the polynomial degree) is proved for linear convection-diffusion equations in [12], which was latter improved to be sharp of order $k+2$ in [23]. There is another kind of superconvergence, which is measured in the $L^{2}$ norm for post-processed errors. For linear hyperbolic equations, [16] proved that the post-processed solution through a convolution with some kernel functions is of order $2 k+1$ superconvergent to the exact solution. Based on the duality argument and divided different estimates, the post-processing technique is extended to linear convectiondiffusion equations in [19] and nonlinear symmetric systems of hyperbolic conservation laws in [20].

Recently, a systematic way via constructing special interpolation functions was successfully applied to the DG and LDG methods for linear hyperbolic and parabolic equations in [5,6]. Moreover, for nonlinear scalar conservation laws, by suitably choosing a local projection and analyzing correction functions, [4] proved that the order between the DG solution and the particular projection can achieves $(k+2)$ th order when the direction of the flow doesn't change, and the order is less than $k+2$ when $f^{\prime}(u)$ changes its sign. Also, the DG flux function $f\left(u_{h}\right)$ is proved to be superconvergent to a particular flux function of the exact solution.

In current paper, we aim at analyzing the superconvergence properties of LDG methods for nonlinear convection-diffusion equations. Different from using a weighed projection and a special operator for constructing correction function when $f^{\prime}(u)$ is fixed or introducing a special projection consisting of four local projections when $f^{\prime}(u)$ does change its sign in [4], we propose a new approach based on the balance of leading errors between the nonlinear
convection term and the diffusion term. To this end, we construct a new combined projection $\Pi(u, q)=\left(P_{h}^{-} u, \mathbb{P}_{h}^{+} q\right)$ depending on the "reference" numerical flux $\tilde{f}$. To be more specific, the standard local Gauss-Radau projection $P_{h}^{-} u$ is used to eliminate the boundary term and integral term resulting from the prime variable $u$ for the diffusion term, while $\mathbb{P}_{h}^{+}$plays the role in dealing with difficulties coming from the auxiliary variable $q$ and the nonlinear convection term $f(u)$. When the direction of the flow doesn't change, the projection $\mathbb{P}_{h}^{+}$is $(k+2)$ th order superclose to the local Gauss-Radau projection $P_{h}^{+}$. Further, some special interpolation functions consisting of the difference between the newly designed projections and correction functions are constructed. The interpolation function is thus superclose to the LDG solution, and superconvergence results can be obtained, which provides a solid foundation for illustrating the inherent interactive mechanism of the leading errors between the nonlinear convection term and the diffusion term.

An overview of this paper is as follows. In Sect 2, we present the semi-discrete LDG method for nonlinear convection-diffusion problems. In Sect. 3, we introduce a new projection and construct special correction functions, and the corresponding properties are analyzed. Section 4 is devoted to the superconvergence analysis, in which we show superconvergence for cell averages, Radau points as well as supercloseness. Extensions of the results to generalized alternating fluxes, mixed boundary conditions and the auxiliary variable are given in Sect. 5. In Sect. 6, numerical experiments are displayed that demonstrate the sharpness of our theoretical results. We end in Sect. 7 with concluding remarks and some possible future work.

## 2 The LDG Scheme

The usual notations of the LDG method are adopted here. For any positive integer $r$, we denote $\mathbb{Z}_{r}=\{0,1, \ldots, r\}$ and $\mathbb{Z}_{r}^{+}=\mathbb{Z}_{r} \backslash\{0\}$. The computational domain $\Omega=[0,2 \pi]$ is divided into $N$ elements with $0=x_{\frac{1}{2}}<x_{\frac{3}{2}}<\cdots<x_{N+\frac{1}{2}}=2 \pi$, The cell center and cell length are denoted by $x_{j}=\frac{1}{2}\left(x_{j-\frac{1}{2}}+x_{j+\frac{1}{2}}\right)$ and $h_{j}=x_{j+\frac{1}{2}}-x_{j-\frac{1}{2}}$, respectively. The following polynomial space is chosen as the finite element space

$$
V_{h}^{k}=\left\{v \in L^{2}(\Omega):\left.v\right|_{I_{j}} \in P^{k}\left(I_{j}\right), \quad j \in \mathbb{Z}_{N}^{+}\right\}
$$

with $P^{k}\left(I_{j}\right)$ the set of polynomials of degree up to $k$ defined on $I_{j}$. Since functions in $V_{h}^{k}$ may be discontinuous across element boundaries, we use

$$
\{\{v\}\}_{j+\frac{1}{2}}=\frac{1}{2}\left(v_{j+\frac{1}{2}}^{+}+v_{j+\frac{1}{2}}^{-}\right), \quad \llbracket v \rrbracket_{j+\frac{1}{2}}=v_{j+\frac{1}{2}}^{+}-v_{j+\frac{1}{2}}^{-}
$$

to denote the mean and jump of the function $v$ at each element boundary point $x_{j+\frac{1}{2}}$, where $v_{j+\frac{1}{2}}^{+}$and $v_{j+\frac{1}{2}}^{-}$are the traces from the right and left cells.

Throughout this paper, we use $W^{\ell, p}(D)$ to denote the standard Sobolev space on $D$ equipped with the norm $\|\cdot\|_{W^{\ell, p}(D)}=\|\cdot\|_{\ell, p, D}$ with $\ell \geq 0, p=2$ and $p=\infty$. For $p=2,\|\cdot\|_{W^{\ell, 2}(D)}=\|\cdot\|_{\ell, D}$, and the subscript $D$ will be omitted when $D=\Omega$ with an unmarked norm $\|\cdot\|$ denoting the standard $L^{2}$ norm on $\Omega$. For $v \in H^{1}(\Omega)$, the $L^{2}$ norm at cell boundaries is defined as follows:

$$
\|v\|_{\Gamma_{h}}=\left(\sum_{j=1}^{N}\left[\left(v_{j-\frac{1}{2}}^{+}\right)^{2}+\left(v_{j+\frac{1}{2}}^{-}\right)^{2}\right]\right)^{\frac{1}{2}} .
$$

As usual, by introducing an auxiliary variable $q=\sqrt{b} u_{x}$, the problem (1.1) can be written as a first order system

$$
u_{t}+f(u)_{x}-\sqrt{b} q_{x}=g(x, t), \quad q-\sqrt{b} u_{x}=0 .
$$

Then the semi-discrete LDG scheme is formulated as follows: find $u_{h}, q_{h} \in V_{h}^{k}$ such that for $\forall v, \varphi \in V_{h}^{k}$

$$
\begin{align*}
& \int_{I_{j}}\left(u_{h}\right)_{t} v \mathrm{~d} x+\left.\hat{f}\left(u_{h}\right) v^{-}\right|_{j+\frac{1}{2}}-\left.\hat{f}\left(u_{h}\right) v^{+}\right|_{j-\frac{1}{2}}-\int_{I_{j}} f\left(u_{h}\right) v_{x} \mathrm{~d} x \\
& \quad-\sqrt{b}\left(\left.\hat{q}_{h} v^{-}\right|_{j+\frac{1}{2}}-\left.\hat{q}_{h} v^{+}\right|_{j-\frac{1}{2}}-\int_{I_{j}} q_{h} v_{x} \mathrm{~d} x\right)=\int_{I_{j}} g(x, t) v \mathrm{~d} x,  \tag{2.1a}\\
& \int_{I_{j}} q_{h} \varphi \mathrm{~d} x-\sqrt{b}\left(\left.\hat{u}_{h} \varphi^{-}\right|_{j+\frac{1}{2}}-\left.\hat{u}_{h} \varphi^{+}\right|_{j-\frac{1}{2}}-\int_{I_{j}} u_{h} \varphi_{x} \mathrm{~d} x\right)=0, \tag{2.1b}
\end{align*}
$$

where $\hat{f}\left(u_{h}\right)$ is the Godunov flux, i.e.,

$$
\hat{f}\left(u_{h}\right) \triangleq \hat{f}\left(u_{h}^{-}, u_{h}^{+}\right)= \begin{cases}\min _{u_{h}^{-} \leq \omega \leq u_{h}^{+}} f(\omega), & \text { if } u_{h}^{-}<u_{h}^{+}, \\ \max _{u_{h}^{+} \leq \omega \leq u_{h}^{-}} f(\omega), & \text { if } u_{h}^{-} \geq u_{h}^{+},\end{cases}
$$

and $\hat{u}_{h}, \hat{q}_{h}$ are a pair of alternating fluxes. For example, one can use the following alternating fluxes

$$
\begin{equation*}
\hat{u}_{h}=u_{h}^{-}, \quad \hat{q}_{h}=q_{h}^{+}, \tag{2.2a}
\end{equation*}
$$

or

$$
\begin{equation*}
\hat{u}_{h}=u_{h}^{+}, \quad \hat{q}_{h}=q_{h}^{-} . \tag{2.2b}
\end{equation*}
$$

Motivated by [4], to deal with the nonlinear term, a "reference" numerical flux is introduced, which plays an important role in the design of new projections in Sect. 3.1 below. That is,

$$
\tilde{f}\left(u_{h}\right)= \begin{cases}f\left(u_{h}^{-}\right), & \text {if }\left.f^{\prime}(u)\right|_{j+\frac{1}{2}} \geq 0,  \tag{2.3}\\ f\left(u_{h}^{+}\right), & \text {if }\left.f^{\prime}(u)\right|_{j+\frac{1}{2}}<0,\end{cases}
$$

where $u_{h}$ and $u$ are the numerical solution and the exact solution of (1.1), respectively.
The LDG scheme (2.1) will be simplified if one adopts the DG spatial discretization operator given by

$$
\mathcal{H}(w, v ; \hat{w})=\sum_{j=1}^{N} \mathcal{H}_{j}(w, v ; \hat{w})
$$

with

$$
\begin{equation*}
\mathcal{H}_{j}(w, v ; \hat{w})=-\left(w, v_{x}\right)_{j}+\left.\hat{w} v^{-}\right|_{j+\frac{1}{2}}-\left.\hat{w} v^{+}\right|_{j-\frac{1}{2}}, \tag{2.4}
\end{equation*}
$$

where $(\cdot, \cdot)_{j}$ denotes the $L^{2}$ inner product on $I_{j}$. By Galerkin orthogonality, one has the following cell error equation

$$
\begin{align*}
\left(\left(e_{u}\right)_{t}, v\right)_{j}+\left(e_{q}, \varphi\right)_{j} & +\mathcal{H}_{j}\left(f(u)-f\left(u_{h}\right), v ; f(u)-\hat{f}\left(u_{h}\right)\right) \\
& -\sqrt{b} \mathcal{H}_{j}\left(e_{q}, v ; \hat{e}_{q}\right)-\sqrt{b} \mathcal{H}_{j}\left(e_{u}, \varphi ; \hat{e}_{u}\right)=0, \tag{2.5}
\end{align*}
$$

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which holds for $\forall v, \varphi \in V_{h}^{k}$ and $j \in \mathbb{Z}_{N}^{+}$. Here $e_{u}=u-u_{h}, e_{q}=q-q_{h}$. In what follows, let us recall the local Gauss-Radau projections of a function $\phi \in H^{1}(\Omega)$ into the finite element space $V_{h}^{k}$, denoted by $P_{h}^{-}$or $P_{h}^{+}$, which are defined as the unique function in $V_{h}^{k}$ such that

$$
\begin{array}{lll}
\left(P_{h}^{-} \phi, v_{h}\right)_{j}=\left(\phi, v_{h}\right)_{j}, & \forall v_{h} \in P^{k-1}\left(I_{j}\right), & P_{h}^{-} \phi\left(x_{j+\frac{1}{2}}^{-}\right)=\phi\left(x_{j+\frac{1}{2}}^{-}\right), \\
\left(P_{h}^{+} \phi, v_{h}\right)_{j}=\left(\phi, v_{h}\right)_{j}, & \forall v_{h} \in P^{k-1}\left(I_{j}\right), & P_{h}^{+} \phi\left(x_{j-\frac{1}{2}}^{+}\right)=\phi\left(x_{j-\frac{1}{2}}^{+}\right) . \tag{2.6b}
\end{array}
$$

To facilitate analysis, we use the following Legendre expansion in each element $I_{j}, j \in$ $\mathbb{Z}_{N}^{+}$. That is, for $\phi \in H^{1}\left(I_{j}\right)$

$$
\phi(x, t)=\sum_{m=0}^{\infty} \phi_{j, m}(t) L_{j, m}(x), \quad \phi_{j, m}(t)=\frac{2 m+1}{h_{j}}\left(\phi, L_{j, m}\right)_{j},
$$

where $L_{j, m}$ denotes the rescaled Legendre polynomial of degree $m$ on $I_{j}$, namely $L_{j, m}(x)=$ $L_{m}\left(\frac{2\left(x-x_{j}\right)}{h_{j}}\right)$. By the definition of $P_{h}^{-}, P_{h}^{+}$in combination with the orthogonality property of Legendre polynomials, one has

$$
\begin{align*}
& \left(\phi-P_{h}^{-} \phi\right)(x, t)=\vec{\phi}_{j, k} L_{j, k}+\sum_{m=k+1}^{\infty} \phi_{j, m} L_{j, m},  \tag{2.7a}\\
& \left(\phi-P_{h}^{+} \phi\right)(x, t)=\overleftarrow{\phi}_{j, k} L_{j, k}+\sum_{m=k+1}^{\infty} \phi_{j, m} L_{j, m} \tag{2.7b}
\end{align*}
$$

in which $\vec{\phi}_{j, k}, \overleftarrow{\phi}_{j, k}$ can be determined by the boundary collocation conditions in (2.6). It reads,

$$
\begin{equation*}
\vec{\phi}_{j, k}=\sum_{m=0}^{k} \phi_{j, m}-\phi\left(x_{j+\frac{1}{2}}^{-}\right), \quad \overleftarrow{\phi}_{j, k}=\sum_{m=0}^{k}(-1)^{k-m} \phi_{j, m}-(-1)^{k} \phi\left(x_{j-\frac{1}{2}}^{+}\right) \tag{2.7c}
\end{equation*}
$$

After a simple application of the Bramble-Hilbert lemma [1, Lemma 2.2.2] and scaling arguments, we obtain

$$
\left|\vec{\phi}_{j, k}\right| \leq C h^{k+1}\|\phi\|_{k+1, \infty}, \quad\left|\overleftarrow{\phi}_{j, k}\right| \leq C h^{k+1}\|\phi\|_{k+1, \infty}
$$

where $C$ is a constant independent of $\phi$ and the mesh size $h$.
For the correction function construction procedure, the following integral operator $D_{x}^{-1}$ is essential, which aims at eliminating the leading term of the error equation via integration by parts, and thus superconvergence results can be obtained; see, e.g., [6]. That is,

$$
D_{x}^{-1} \phi(x)=\frac{1}{\bar{h}_{j}} \int_{x_{j-\frac{1}{2}}}^{x} \phi(\tau) \mathrm{d} \tau, \quad \tau \in I_{j},
$$

where $\bar{h}_{j}=h_{j} / 2$. Obviously,

$$
\begin{equation*}
\phi(x)=\bar{h}_{j}\left(D_{x}^{-1} \phi(x)\right)_{x} . \tag{2.8}
\end{equation*}
$$

Moreover, by the properties of Legendre polynomials, for $m \in \mathbb{Z}_{k}$ with $L_{j,-1}=0$, we have

$$
\begin{equation*}
D_{x}^{-1} L_{j, m}(x)=\frac{1}{2 m+1}\left(L_{j, m+1}-L_{j, m-1}\right)(x) . \tag{2.9}
\end{equation*}
$$

Finally, we list some inverse properties of the element space $V_{h}^{k}$ that will be used in our analysis. For any $v_{h} \in V_{h}^{k}$, there exists a positive constant $C$ independent of $v_{h}$ and $h$ such that
(i) $\left\|\partial_{x} v_{h}\right\| \leq C h^{-1}\left\|v_{h}\right\| ;$ (ii) $\left\|v_{h}\right\|_{\Gamma_{h}} \leq C h^{-1 / 2}\left\|v_{h}\right\| ;$ (iii) $\left\|v_{h}\right\|_{\infty} \leq C h^{-1 / 2}\left\|v_{h}\right\|$.

## 3 A New Projection and Correction Functions

To derive superconvergence results, interpolation functions consisting of special projections and correction functions need to be carefully designed, which are mainly used to obtain a superconvergent bound for the contribution of projection errors; see Sect. 3.3 below. Since the Gauss-Radau projections $P_{h}^{-}$or $P_{h}^{+}$are not sufficient to deal with the nonlinear term that changes its flow direction, we shall first introduce a new projection, which is a modification of $P_{h}^{+}$. In what follows, we mainly concentrate on the fluxes (2.2a), and the case with (2.2b) will be discussed in Remark 3.2.

### 3.1 A New Projection

Motivated by [11, Sect. 4.2], we define the following modified projection

$$
\Pi(u, q)=\left(P_{h}^{-} u, \mathbb{P}_{h}^{+} q\right)
$$

where $P_{h}^{-} u \in V_{h}^{k}$ has been given in (2.6a), and $\mathbb{P}_{h}^{+} q \in V_{h}^{k}$ depends on both $u$ and $q$ such that

$$
\begin{align*}
& \int_{I_{j}}\left(q-\mathbb{P}_{h}^{+} q\right) v_{h} \mathrm{~d} x-\frac{1}{\sqrt{b}} \int_{I_{j}} f^{\prime}(u)\left(u-P_{h}^{-} u\right) v_{h} \mathrm{~d} x=0, \quad \forall v_{h} \in P^{k-1}\left(I_{j}\right),  \tag{3.1a}\\
& \mathbb{P}_{h}^{+} q\left(x_{j-\frac{1}{2}}^{+}\right)=q\left(x_{j-\frac{1}{2}}^{+}\right)-\frac{1}{\sqrt{b}} f^{\prime}\left(u_{j-\frac{1}{2}}\right)\left(u-P_{h}^{-} u\right)_{j-\frac{1}{2}}, \quad \forall j \in \mathbb{Z}_{N}^{+}, \tag{3.1b}
\end{align*}
$$

where $\widetilde{w}$ has been defined in (2.3). It is easy to see that $\mathbb{P}_{h}^{+} q=P_{h}^{+} q$ when $f^{\prime}(u)=0$, and $\left(q-\mathbb{P}_{h}^{+} q\right)_{j-\frac{1}{2}}^{+}=0$ when $f^{\prime}(u) \geq 0$. Thus, $\mathbb{P}_{h}^{+}$can be viewed as an extension of the local Gauss-Radau projection $P_{h}^{+}$. Moreover, for $v \in V_{h}^{k}$ and $j \in \mathbb{Z}_{N}^{+}, \Pi(u, q)=\left(P_{h}^{-} u, \mathbb{P}_{h}^{+} q\right)$ satisfies the following identity

$$
\mathcal{H}_{j}\left(f^{\prime}(u)\left(u-P_{h}^{-} u\right), v ; f^{\prime}(u)\left(\overline{-P_{h}^{-}} u\right)\right)-\sqrt{b} \mathcal{H}_{j}\left(q-\mathbb{P}_{h}^{+} q, v ;\left(q-\mathbb{P}_{h}^{+} q\right)^{+}\right)=0 .(3.2)
$$

The properties of the projection $\mathbb{P}_{h}^{+}$in the following lemma are essential to the proof of superconvergence; see Lemma 3.3 below.

Lemma 3.1 Suppose $\left|\partial_{x}^{k} f^{\prime}(u)\right| \leq C$, then the projection $\mathbb{P}_{h}^{+}$in (3.1) is well defined. Moreover, if $q-\mathbb{P}_{h}^{+} q$ has the following expression in each element $I_{j}$

$$
\begin{equation*}
q-\left.\mathbb{P}_{h}^{+} q\right|_{I_{j}}=\sum_{m=0}^{k} \bar{q}_{j, m} L_{j, m}+\sum_{m=k+1}^{\infty} q_{j, m} L_{j, m}, \tag{3.3}
\end{equation*}
$$

then there holds the following results:

## (i) Springer

(1) The coefficients $\bar{q}_{j, m}$ satisfies

$$
\begin{equation*}
\left|\bar{q}_{j, m}\right| \leq C h^{2 k+1-m}\|u\|_{k+2, \infty}, \quad m \in \mathbb{Z}_{k} \tag{3.4}
\end{equation*}
$$

(2) The cell average of the projection error $q-\mathbb{P}_{h}^{+} q$ in each element $I_{j}$ is superconvergent with an order of $2 k+1$, i.e.,

$$
\left|\frac{1}{h_{j}} \int_{I_{j}}\left(q-\mathbb{P}_{h}^{+} q\right)(x) \mathrm{d} x\right| \leq C h^{2 k+1}\|u\|_{k+2, \infty} .
$$

Especially, when $f^{\prime}(u) \geq 0$, namely $\left(\widetilde{-P_{h}^{-}} u\right)_{j-\frac{1}{2}}=\left(u-P_{h}^{-} u\right)_{j-\frac{1}{2}}^{-}=0$, we have the following supercloseness results.
(3) $\mathbb{P}_{h}^{+} q$ is superclose to the Gauss-Radau projection $P_{h}^{+} q$, i.e.,

$$
\begin{equation*}
\left\|\mathbb{P}_{h}^{+} q-P_{h}^{+} q\right\|_{\infty} \leq C h^{k+2}\|u\|_{k+2, \infty} . \tag{3.5}
\end{equation*}
$$

(4) The function value approximation of $\mathbb{P}_{h}^{+} q$ is superconvergent at left Radau points $\ell_{j, m}, m \in \mathbb{Z}_{k}^{+}$(zeros of left Radau polynomial $L_{j, m+1}+L_{j, m}$ ), and the derivative value approximation is superconvergent at the interior right Radau points $r_{j, m}, m \in \mathbb{Z}_{k}^{+}$(zeros of right Radau polynomial $L_{j, m+1}-L_{j, m}$, except the point $x=x_{j+\frac{1}{2}}$, namely

$$
\begin{array}{r}
\left|\left(q-\mathbb{P}_{h}^{+} q\right)\left(\ell_{j, m}\right)\right| \leq C h^{k+2}\|q\|_{k+2, \infty}, \\
\left|\partial_{x}\left(q-\mathbb{P}_{h}^{+} q\right)\left(r_{j, m}\right)\right| \leq C h^{k+1}\|q\|_{k+2, \infty} \tag{3.6b}
\end{array}
$$

The constant $C$ is independent of $h$.
Proof (1) Since $\mathbb{P}_{h}^{+} q \in V_{h}^{k}$, we express in each element $I_{j}$

$$
\begin{equation*}
\left.\mathbb{P}_{h}^{+} q\right|_{I_{j}}=\sum_{m=0}^{k} b_{j, m} L_{j, m}, \tag{3.7}
\end{equation*}
$$

where $b_{j, m}$ are coefficients to be determined later. Using the orthogonality of Legendre polynomials, (3.1a), and (2.6a), we obtain, for $\forall m \in \mathbb{Z}_{k-1}$

$$
\begin{aligned}
\bar{q}_{j, m} & =\frac{2 m+1}{h_{j}} \int_{I_{j}}\left(q-\mathbb{P}_{h}^{+} q\right) L_{j, m} \mathrm{~d} x \\
& =\frac{2 m+1}{\sqrt{b} h_{j}} \int_{I_{j}} f^{\prime}(u)\left(u-P_{h}^{-} u\right) L_{j, m} \mathrm{~d} x \\
& =\frac{2 m+1}{\sqrt{b} h_{j}} \int_{I_{j}}\left(f^{\prime}(u)-I_{k-1-m} f^{\prime}(u)\right)\left(u-P_{h}^{-} u\right) L_{j, m} \mathrm{~d} x .
\end{aligned}
$$

Here and below, $I_{m} w \in P^{m}\left(I_{j}\right)$ represents an interpolation of $w$. By the Bramble-Hilbert lemma,

$$
\left\|f^{\prime}(u)-I_{k-1-m} f^{\prime}(u)\right\|_{\infty, I_{j}} \leq C h^{k-m}\left\|\partial_{x}^{k-m} f^{\prime}(u)\right\|_{\infty} \leq C h^{k-m},
$$

which yields

$$
\begin{equation*}
\left|\bar{q}_{j, m}\right| \leq C h^{k-m}\left\|u-P_{h}^{-} u\right\|_{\infty, I_{j}} \leq C h^{2 k+1-m}\|u\|_{k+1, \infty}, m \in \mathbb{Z}_{k-1} \tag{3.8}
\end{equation*}
$$

Next, let us consider the estimate to $\bar{q}_{j, k}$. On the one hand, by (3.7), using the definition of $\mathbb{P}_{h}^{+}$in (3.1b) and the fact that $(-1)^{2 m}=1\left(\forall m \in \mathbb{Z}_{k-1}\right)$, we get

$$
b_{j, k}=(-1)^{k} q\left(x_{j-\frac{1}{2}}^{+}\right)-\sum_{m=0}^{k-1}(-1)^{k-m} b_{j, m}-\Phi
$$

where

$$
\Phi=(-1)^{k} \frac{1}{\sqrt{b}} f^{\prime}(u)\left(\widetilde{-P_{h}^{-}} u\right)_{j-\frac{1}{2}} .
$$

On the other hand, it follows from $q_{j, k}=-(-1)^{k}(-1)^{k+1} q_{j, k}$ and the expression for $\overleftarrow{q}_{j, k}$ in (2.7c) that

$$
\begin{align*}
\bar{q}_{j, k}=q_{j, k}-b_{j, k} & =q_{j, k}+(-1)^{k+1} q\left(x_{j-\frac{1}{2}}^{+}\right)+\sum_{m=0}^{k-1}(-1)^{k-m} b_{j, m}+\Phi \\
& =(-1)^{k+1}\left(q\left(x_{j-\frac{1}{2}}^{+}\right)-\sum_{m=0}^{k}(-1)^{m} q_{j, m}+\sum_{m=0}^{k-1}(-1)^{m} \bar{q}_{j, m}\right)+\Phi \\
& =\overleftarrow{q}_{j, k}+\sum_{m=0}^{k-1}(-1)^{k-m+1} \bar{q}_{j, m}+\Phi \tag{3.9}
\end{align*}
$$

where we have also used the relation $b_{j, m}=q_{j, m}-\bar{q}_{j, m}, m \in \mathbb{Z}_{k-1}$. Moreover,

$$
|\Phi| \leq\left\|u-P_{h}^{-} u\right\|_{\infty} \leq C h^{k+1}\|u\|_{k+1, \infty}
$$

Consequently,

$$
\left|\bar{q}_{j, k}\right| \leq\left|\overleftarrow{q}_{j, k}\right|+\sum_{m=0}^{k-1}\left|\bar{q}_{j, m}\right|+|\Phi| \leq C h^{k+1}\|u\|_{k+2, \infty}
$$

This completes the proof of (3.4).
(2) Using (3.3) and (3.4) in combination with the orthogonality property of Legendre polynomials, we have

$$
\left|\frac{1}{h_{j}} \int_{I_{j}}\left(q-\mathbb{P}_{h}^{+} q\right) \mathrm{d} x\right|=\frac{1}{h_{j}}\left|\int_{I_{j}} \bar{q}_{j, 0} \mathrm{~d} x\right| \leq\left|\bar{q}_{j, 0}\right| \leq C h^{2 k+1}\|u\|_{k+2, \infty} .
$$

(3) When $f^{\prime}(u) \geq 0$, namely $\left(u-P_{h}^{-} u\right)_{j-\frac{1}{2}}=0$, then $\Phi=0$, and we can express $P_{h}^{+} q$ in terms of the orthogonal basis $L_{j, m}\left(m \in \mathbb{Z}_{k}\right)^{2}$ as

$$
P_{h}^{+} q=\sum_{m=0}^{k} q_{j, m} L_{j, m}-\overleftarrow{q}_{j, k} L_{j, k}
$$

with $\overleftarrow{q}_{j, k}$ defined in (2.7c). This, together with (3.7) and (3.9), leads to

$$
\begin{aligned}
P_{h}^{+} q-\mathbb{P}_{h}^{+} q & =\sum_{m=0}^{k-1}\left(q_{j, m}-b_{j, m}\right) L_{j, m}+\left(\bar{q}_{j, k}-\overleftarrow{q}_{j, k}\right) L_{j, k}, \\
& =\sum_{m=0}^{k-1} \bar{q}_{j, m} L_{j, m}+\sum_{m=0}^{k-1}(-1)^{k-m+1} \bar{q}_{j, m} L_{j, k},
\end{aligned}
$$

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where we have used the fact that $q_{j, m}-b_{j, m}=\bar{q}_{j, m}, m \in \mathbb{Z}_{k}$. Then, by (3.4)

$$
\left\|P_{h}^{+} q-\mathbb{P}_{h}^{+} q\right\|_{\infty, I_{j}} \leq \sum_{m=0}^{k-1}\left|\bar{q}_{j, m}\right| \leq C h^{k+2}\|u\|_{k+2, \infty}, \quad \forall j \in \mathbb{Z}_{N}
$$

This finishes the proof of (3.5).
(4) The inverse inequality $\left\|\partial_{x}\left(P_{h}^{+} q-\mathbb{P}_{h}^{+} q\right)\right\|_{\infty, I_{j}} \leq C h^{k+1}\|u\|_{k+2, \infty}$ together with the superconvergence results for $P_{h}^{+}$in [7], namely

$$
\left|\left(q-P_{h}^{+} q\right)\left(\ell_{j, m}\right)\right| \leq C h^{k+2}\|q\|_{k+2, \infty}, \quad\left|\partial_{x}\left(q-P_{h}^{+} q\right)\left(r_{j, m}\right)\right| \leq C h^{k+1}\|q\|_{k+2, \infty}
$$ gives us the desired results (3.6). This completes the proof of Lemma 3.1.

### 3.2 Correction Functions

In order to construct the interpolation functions $\left(u_{I}^{\ell}, q_{I}^{\ell}\right)$, let us begin by defining a series of functions $w_{u, i}, w_{q, i} \in V_{h}^{k}, i \in \mathbb{Z}_{k}^{+}$as follows

$$
\begin{array}{ll}
\left(\sqrt{b} w_{u, i}-\bar{h}_{j} D_{x}^{-1} w_{q, i-1}, v\right)_{j}=0, & \left(w_{u, i}^{-}\right)_{j+\frac{1}{2}}=0, \\
\left(\sqrt{b} w_{q, i}-f^{\prime}(u) w_{u, i}-\bar{h}_{j} D_{x}^{-1} \partial_{t} w_{u, i-1}, v\right)_{j}=0, & \left(w_{q, i}^{+}\right)_{j-\frac{1}{2}}=\frac{1}{\sqrt{b}}\left(f^{\prime}(u) \widetilde{w}_{u, i}\right)_{j-\frac{1}{2}}, \tag{3.10b}
\end{array}
$$

where $v \in P^{k-1}\left(I_{j}\right)$, and

$$
w_{u, 0}=u-P_{h}^{-} u, \quad w_{q, 0}=q-\mathbb{P}_{h}^{+} q .
$$

Further, for any positive integer $\ell \in \mathbb{Z}_{k}^{+}$, we define in each element $I_{j}$ the correction functions

$$
\begin{equation*}
W_{u}^{\ell}=\sum_{i=1}^{\ell} w_{u, i}, \quad W_{q}^{\ell}=\sum_{i=1}^{\ell} w_{q, i} \tag{3.11}
\end{equation*}
$$

and the special interpolation functions are

$$
\begin{equation*}
u_{I}^{\ell}=P_{h}^{-} u-W_{u}^{\ell}, \quad q_{I}^{\ell}=\mathbb{P}_{h}^{+} q-W_{q}^{\ell} . \tag{3.12}
\end{equation*}
$$

The components $w_{u, i}, w_{q, i}$ in correction functions have the following property.
Lemma 3.2 The functions $w_{u, i}, w_{q, i}, i \in \mathbb{Z}_{k}^{+}$defined in (3.10) are uniquely determined. Moreover, suppose that $f^{\prime}(u)$ is a sufficiently smooth function satisfying

$$
\left|\partial_{x}^{k+1} f^{\prime}(u)\right| \leq C, \quad\left|\partial_{t}^{k+1} f^{\prime}(u)\right| \leq C,
$$

and the functions $w_{u, i}$ and $w_{q, i}$ in each element $I_{j}$ are expressed by

$$
\left.w_{u, i}\right|_{I_{j}}=\sum_{m=0}^{k} \beta_{i, m} L_{j, m},\left.\quad w_{q, i}\right|_{I_{j}}=\sum_{m=0}^{k} \gamma_{i, m} L_{j, m} .
$$

Then, the coefficients $\beta_{i, m}$ and $\gamma_{i, m}$ satisfy

$$
\begin{align*}
& \left|\partial_{t}^{n} \beta_{i, m}\right| \leq C h^{\max \{k+1+i, 2 k+1-m\}}\left\|\partial_{t}^{n} u\right\|_{k+i+1, \infty}, n=0,1,  \tag{3.13a}\\
& \left|\partial_{t}^{n} \gamma_{i, m}\right| \leq C h^{\max \{k+1+i, 2 k+1-m\}}\left\|\partial_{t}^{n} u\right\|_{k+i+2, \infty}, n=0,1 . \tag{3.13b}
\end{align*}
$$

As a consequence,

$$
\begin{align*}
\left\|\partial_{t} w_{u, i}\right\|_{\infty}+\left\|w_{q, i}\right\|_{\infty} & \leq C h^{k+i+1}\|u\|_{k+i+3, \infty},  \tag{3.1.1a}\\
\left\|W_{u}^{\ell}\right\|_{\infty}+\left\|W_{q}^{\ell}\right\|_{\infty} & \leq C h^{k+2}\|u\|_{k+\ell+3, \infty} \tag{3.14b}
\end{align*}
$$

Proof We prove this lemma by induction, consisting of the following two steps. Since the case with $n=1$ is quite similar to that with $n=0$, we mainly consider the case with $n=0$.

Step 1: When $i=1$, taking $v=L_{j, m}, m \in \mathbb{Z}_{k-1}$ in (3.10a) and using the orthogonality property of Legendre polynomials, we get

$$
\left(\sqrt{b} w_{u, 1}-\bar{h}_{j} D_{x}^{-1} w_{q, 0}, v\right)_{j}=\left(\sqrt{b} \sum_{m=0}^{k} \beta_{1, m} L_{j, m}-\bar{h}_{j} \sum_{m=0}^{k} \bar{q}_{j, m} D_{x}^{-1} L_{j, m}, v\right)_{j}=0,
$$

where $\bar{q}_{j, m}$ are the coefficients defined in (3.3). Using the relation (2.9) and the orthogonality property of Legendre polynomials again, we arrive at

$$
\begin{aligned}
& \sqrt{b} \beta_{1,0}=-\frac{\bar{q}_{j, 1}}{3} \bar{h}_{j}, \\
& \sqrt{b} \beta_{1, m}=\frac{\bar{q}_{j, m-1}}{2 m-1} \bar{h}_{j}-\frac{\bar{q}_{j, m+1}}{2 m+3} \bar{h}_{j}, m \in \mathbb{Z}_{k-1}^{+} .
\end{aligned}
$$

Using (3.8), we have

$$
\begin{aligned}
\left|\beta_{1,0}\right| & \leq h\left|\bar{q}_{j, 1}\right| \leq C h^{2 k+1}\|u\|_{k+1, \infty} \\
\left|\beta_{1, m}\right| & \leq h\left(\left|\bar{q}_{j, m-1}\right|+\left|\bar{q}_{j, m+1}\right|\right) \leq C h^{2 k+1-m}\|u\|_{k+1, \infty}, m \in \mathbb{Z}_{k-1}^{+}
\end{aligned}
$$

Using the fact that $\left(w_{u, 1}^{-}\right)_{j+\frac{1}{2}}=0$, we obtain

$$
\left|\beta_{1, k}\right|=\left|\sum_{m=0}^{k-1} \beta_{1, m}\right| \leq \sum_{m=0}^{k-1}\left|\beta_{1, m}\right| \leq C h^{k+2}\|u\|_{k+2, \infty}
$$

Analogously, taking $v=L_{j, m}, m \in \mathbb{Z}_{k-1}$ in (3.10b) and using (2.7a) as well as (2.9), we get

$$
\begin{aligned}
\sqrt{b} \gamma_{1, m} & =\frac{2 m+1}{h_{j}}\left(f^{\prime}(u) w_{u, 1}, L_{j, m}\right)_{j}, \quad m \in \mathbb{Z}_{k-2}, \\
\sqrt{b} \gamma_{1, k-1} & =\frac{2 k-1}{h_{j}}\left(f^{\prime}(u) w_{u, 1}, L_{j, k-1}\right)_{j}-\frac{\bar{h}_{j} \partial_{t} \vec{u}_{j, k}}{2 k+1} .
\end{aligned}
$$

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Specifically, when $m \in \mathbb{Z}_{k-2}$, we have

$$
\begin{aligned}
\left|\sqrt{b} \gamma_{1, m}\right|= & \left|\frac{2 m+1}{h_{j}} \sum_{\nu=0, v \neq m}^{k}\left(f^{\prime}(u) \beta_{1, v} L_{j, v}, L_{j, m}\right)_{j}+\frac{2 m+1}{h_{j}}\left(f^{\prime}(u) \beta_{1, m} L_{j, m}, L_{j, m}\right)_{j}\right| \\
= & \left\lvert\, \frac{2 m+1}{h_{j}} \sum_{\nu=0, v \neq m}^{k}\left(\left(f^{\prime}(u)-I_{|\nu-m|-1} f^{\prime}(u)\right) \beta_{1, \nu} L_{j, v}, L_{j, m}\right)_{j}\right. \\
& \left.+\frac{2 m+1}{h_{j}}\left(f^{\prime}(u) \beta_{1, m} L_{j, m}, L_{j, m}\right)_{j} \right\rvert\, \\
\leq & \left|\frac{2 m+1}{h_{j}} \sum_{\nu=0, v \neq m}^{k}\left(\left(f^{\prime}(u)-I_{|v-m|-1} f^{\prime}(u)\right) \beta_{1, \nu} L_{j, v}, L_{j, m}\right)_{j}\right|+C\left|\beta_{1, m}\right| \\
\leq & \sum_{\nu=0, v \neq m}^{k} C h^{|\nu-m|}\left|\beta_{1, v}\right|+C\left|\beta_{1, m}\right|,
\end{aligned}
$$

where in the second step we have used the orthogonality property of Legendre polynomials, in the third step we have employed Hölder's inequality and in the last step we have used the following interpolation error estimate

$$
\left\|f^{\prime}(u)-I_{|\nu-m|-1} f^{\prime}(u)\right\|_{\infty} \leq C h^{|\nu-m|}\left\|\partial_{x}^{|\nu-m|} f^{\prime}(u)\right\|_{\infty} \leq C h^{|\nu-m|} .
$$

It is easy to see that no matter $v>m$ or $v<m$, the following formula is valid

$$
\left|\gamma_{1, m}\right| \leq C h^{2 k+1-m}\|u\|_{k+2, \infty}, \quad m \in \mathbb{Z}_{k-2} .
$$

By the same arguments, we can obtain

$$
\left|\gamma_{1, k-1}\right| \leq \sum_{\nu=0, \nu \neq k-1}^{k} C h^{|\nu-(k-1)|}\left|\beta_{1, \nu}\right|+C\left|\beta_{1, k-1}\right|+h_{j}\left|\partial_{t} \vec{u}_{j, k}\right| \leq C h^{k+2}\|u\|_{k+3, \infty},
$$

since $\left\|\partial_{t} u\right\|_{k+1, \infty}=\left\|f^{\prime}(u) \partial_{x} u-\partial_{x}^{2} u\right\|_{k+1, \infty} \leq C\|u\|_{k+3, \infty}$. It remains to bound $\gamma_{1, k}$. We use $\left(w_{q, 1}^{+}\right)_{j-\frac{1}{2}}=\frac{1}{\sqrt{b}}\left(f^{\prime}(u) \widetilde{w}_{u, 1}\right)_{j-\frac{1}{2}}$ in (3.10b) to obtain

$$
\left|\gamma_{1, k}\right| \leq \sum_{m=0}^{k-1}\left|\gamma_{1, m}\right|+\sum_{m=0}^{k} C\left|\beta_{1, m}\right| \leq C h^{k+2}\|u\|_{k+3, \infty} .
$$

Therefore, (3.13) is valid for $i=1$.
Step 2: Suppose that (3.13) holds for $i, 1 \leq i \leq k-1$, and we need to prove that it is also valid for $i+1$.

We choose $v=L_{j, m}, m \in \mathbb{Z}_{k-1}$ in (3.10a) to obtain

$$
\begin{aligned}
& \sqrt{b} \beta_{i+1,0}=-\frac{\bar{h}_{j}}{3} \gamma_{i, 1}, \\
& \sqrt{\bar{b}} \beta_{i+1, m}=\frac{\bar{h}_{j} \gamma_{i, m-1}}{2 m-1}-\frac{\bar{h}_{j} \gamma_{i, m+1}}{2 m+3}, m \in \mathbb{Z}_{k-1}^{+} .
\end{aligned}
$$

It is easy to deduce that

$$
\begin{aligned}
& \left|\beta_{i+1,0}\right| \leq h\left|\gamma_{i, 1}\right| \leq C h^{2 k+1}\|u\|_{k+i+2, \infty}, \\
& \left|\beta_{i+1, m}\right| \leq h\left(\left|\gamma_{i, m-1}\right|+\left|\gamma_{i, m+1}\right|\right) \leq C h^{\max \{k+2+i, 2 k+1-m\}}\|u\|_{k+i+2, \infty}, m \in \mathbb{Z}_{k-1}^{+} .
\end{aligned}
$$

Using the fact that $\left(w_{u, i+1}^{-}\right)_{j+\frac{1}{2}}=0$, we get

$$
\left|\beta_{i+1, k}\right|=\left|\sum_{m=0}^{k-1} \beta_{i+1, m}\right| \leq \sum_{m=0}^{k-1}\left|\beta_{i+1, m}\right| \leq C h^{k+2+i}\|u\|_{k+i+2, \infty} .
$$

Analogously, taking $v=L_{j, m}, m \in \mathbb{Z}_{k-1}$ in (3.10b), we have

$$
\begin{aligned}
\sqrt{b} \gamma_{i+1,0} & =\frac{1}{h_{j}}\left(f^{\prime}(u) w_{u, i+1}, L_{j, 0}\right)_{j}-\frac{\bar{h}_{j}}{3} \partial_{t} \beta_{i, 1} \\
\sqrt{b} \gamma_{i+1, m} & =\frac{2 m+1}{h_{j}}\left(f^{\prime}(u) w_{u, i+1}, L_{j, m}\right)_{j}+\frac{\bar{h}_{j} \partial_{t} \beta_{i, m-1}}{2 m-1}-\frac{\bar{h}_{j} \partial_{t} \beta_{i, m+1}}{2 m+3}, \quad m \in \mathbb{Z}_{k-1}^{+} .
\end{aligned}
$$

In particular, when $m \in \mathbb{Z}_{k-1}$, we have

$$
\begin{aligned}
& \left|\frac{2 m+1}{h_{j}}\left(f^{\prime}(u) w_{u, i+1}, L_{j, m}\right)_{j}\right| \\
& \quad=\left|\frac{2 m+1}{h_{j}} \sum_{\nu=0, v \neq m}^{k}\left(f^{\prime}(u) \beta_{i+1, v} L_{j, v}, L_{j, m}\right)_{j}+\frac{2 m+1}{h_{j}}\left(f^{\prime}(u) \beta_{i+1, m} L_{j, m}, L_{j, m}\right)_{j}\right| \\
& \quad \leq\left|\frac{2 m+1}{h_{j}} \sum_{\nu=0, v \neq m}^{k}\left(\left(f^{\prime}(u)-I_{|v-m|-1} f^{\prime}(u)\right) \beta_{i+1, v} L_{j, v}, L_{j, m}\right)_{j}\right|+C\left|\beta_{i+1, m}\right| \\
& \quad \leq \sum_{\nu=0, v \neq m}^{k} C h^{|\nu-m|}\left|\beta_{i+1, v}\right|+C\left|\beta_{i+1, m}\right| \\
& \leq C h^{\max \{k+2+i, 2 k+1-m\}}\|u\|_{k+i+2, \infty} .
\end{aligned}
$$

Consequently,

$$
\begin{aligned}
\left|\gamma_{i+1,0}\right| & \leq C h^{2 k+1}\|u\|_{k+i+2, \infty}+h\left|\partial_{t} \beta_{i, 1}\right| \leq C h^{2 k+1}\|u\|_{k+i+3, \infty}, \\
\left|\gamma_{i+1, m}\right| & \leq C h^{\max \{k+2+i, 2 k+1-m\}}\|u\|_{k+i+2, \infty}+h\left(\left|\partial_{t} \beta_{i, m-1}\right|+\left|\partial_{t} \beta_{i, m+1}\right|\right) \\
& \leq C h^{\max \{k+2+i, 2 k+1-m\}}\|u\|_{k+i+3, \infty}, \quad m \in \mathbb{Z}_{k-1}^{+} .
\end{aligned}
$$

In addition, it follows from (3.10b) that

$$
\left|\gamma_{i+1, k}\right| \leq \sum_{m=0}^{k-1}\left|\gamma_{i+1, m}\right|+\sum_{m=0}^{k} C\left|\beta_{i+1, m}\right| \leq C h^{k+2+i}\|u\|_{k+i+3, \infty} .
$$

Therefore (3.13) holds for $i+1$ and this finishes the proof of Lemma 3.2.

### 3.3 The Superconvergent Bound for the Projection Errors

To clearly see how to cancel terms involving projection errors with the goal of obtaining superconvergence, we split the error $e_{u}, e_{q}$ into two parts:

$$
\begin{aligned}
& e_{u}=u-u_{h}=u-u_{I}^{\ell}+u_{I}^{\ell}-u_{h} \triangleq \eta_{u}+\xi_{u}, \\
& e_{q}=q-q_{h}=q-q_{I}^{\ell}+q_{I}^{\ell}-q_{h} \triangleq \eta_{q}+\xi_{q} .
\end{aligned}
$$

Here $u_{I}^{\ell}$ and $q_{I}^{\ell}$ are the two special interpolation functions of $u$ and $q$ given in (3.12).

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Lemma 3.3 Suppose that $u \in W^{k+\ell+3, \infty}, \ell \in \mathbb{Z}_{k}^{+}$is the exact solution of (1.1), and $u_{I}^{\ell}$, $q_{I}^{\ell}$ are the interpolation functions defined by (3.12), then for $\forall v, \varphi \in V_{h}^{k}$, we have

$$
\begin{aligned}
&\left|\left(\left(\eta_{u}\right)_{t}, v\right)_{j}+\mathcal{H}_{j}\left(f^{\prime}(u) \eta_{u}, v ; f^{\prime}(u) \widetilde{\eta}_{u}\right)-\sqrt{b} \mathcal{H}_{j}\left(\eta_{q}, v ; \eta_{q}^{+}\right)\right| \leq C h^{k+\ell+1}\|u\|_{k+\ell+3, \infty}\|v\|_{1, I_{j}}, \\
&\left|\left(\eta_{q}, \varphi\right)_{j}-\sqrt{b} \mathcal{H}_{j}\left(\eta_{u}, \varphi ; \eta_{u}^{-}\right)\right| \leq C h^{k+\ell+1}\|u\|_{k+\ell+2, \infty}\|\varphi\|_{1, I_{j}} .
\end{aligned}
$$

Proof Since $\eta_{u}=u-P_{h}^{-} u+W_{u}^{\ell}$ and $\eta_{q}=q-\mathbb{P}_{h}^{+} q+W_{q}^{\ell}$, using the identity (3.2), we get

$$
\begin{aligned}
S & \triangleq\left(\left(\eta_{u}\right)_{t}, v\right)_{j}+\mathcal{H}_{j}\left(f^{\prime}(u) \eta_{u}, v ; f^{\prime}(u) \widetilde{\eta}_{u}\right)-\sqrt{b} \mathcal{H}_{j}\left(\eta_{q}, v ; \eta_{q}^{+}\right) \\
& =\left(\left(\eta_{u}\right)_{t}, v\right)_{j}+\mathcal{H}_{j}\left(f^{\prime}(u) W_{u}^{\ell}, v ; f^{\prime}(u) \widetilde{W}_{u}^{\ell}\right)-\sqrt{b} \mathcal{H}_{j}\left(W_{q}^{\ell}, v ;\left(W_{q}^{\ell}\right)+\right),
\end{aligned}
$$

which, by the definition of the DG spatial operator in (2.4) and the boundary collocation for correction functions in (3.10b), is

$$
S=\left(\left(w_{u, 0}+W_{u}^{\ell}\right)_{t}, v\right)_{j}+\left(\sqrt{b} W_{q}^{\ell}-f^{\prime}(u) W_{u}^{\ell}, v_{x}\right)_{j} .
$$

Let us now work on $\left(\partial_{t} w_{u, i}, v\right)_{j}$ for $i \in \mathbb{Z}_{\ell-1}$, which consists of the first term in $S$ except $\left(\partial_{t} w_{u, \ell}, v\right)_{j}$. It follows from (2.8) and integration by parts that

$$
\begin{align*}
\left(\partial_{t} w_{u, i}, v\right)_{j}= & \left(\bar{h}_{j}\left(D_{x}^{-1} \partial_{t} w_{u, i}\right)_{x}, v\right)_{j} \\
= & -\left(\bar{h}_{j} D_{x}^{-1} \partial_{t} w_{u, i}, v_{x}\right)_{j}+\bar{h}_{j} D_{x}^{-1} \partial_{t} w_{u, i}\left(x_{j+\frac{1}{2}}^{-}\right) v\left(x_{j+\frac{1}{2}}^{-}\right) \\
& -\bar{h}_{j} D_{x}^{-1} \partial_{t} w_{u, i}\left(x_{j-\frac{1}{2}}^{+}\right) v\left(x_{j-\frac{1}{2}}^{+}\right) \tag{3.15}
\end{align*}
$$

Consequently, substituting the relation (3.10b) regarding the integral terms and the following boundary values implied by the definition of the integral operator $D_{x}^{-1}$ into (3.15)

$$
\begin{aligned}
& \bar{h}_{j} D_{x}^{-1} \partial_{t} w_{u, i}\left(x_{j+\frac{1}{2}}^{-}\right)=\int_{I_{j}} \sum_{m=0}^{k} \partial_{t} \beta_{i, m} L_{j, m} \mathrm{~d} x=h_{j} \partial_{t} \beta_{i, 0}, \\
& \bar{h}_{j} D_{x}^{-1} \partial_{t} w_{u, i}\left(x_{j-\frac{1}{2}}^{+}\right)=0
\end{aligned}
$$

we obtain

$$
S=\left(\partial_{t} w_{u, \ell}, v\right)_{j}+\sum_{i=0}^{\ell-1} h_{j} \partial_{t} \beta_{i, 0} v\left(x_{j+\frac{1}{2}}^{-}\right) \leq C h^{k+\ell+1}\|u\|_{k+\ell+3, \infty}\|v\|_{1, I_{j}},
$$

where $\beta_{0,0}=0$ due to (2.7a), and we have also used $\left\|\partial_{t} w_{u, \ell}\right\|_{\infty} \leq C h^{k+\ell+1}\|u\|_{k+\ell+3, \infty}$ in (3.14a), the inverse property $\|v\|_{\infty, j} \leq C h_{j}^{-1}\|v\|_{1, I_{j}}$ and the fact that $\left|\partial_{t} \beta_{i, 0}\right| \leq$ $C h^{2 k+1}\|u\|_{k+\ell+3, \infty}$ for $i \in \mathbb{Z}_{\ell-1}^{+}$in (3.13a).

Analogously, there holds

$$
\begin{aligned}
\left|\left(\eta_{q}, \varphi\right)_{j}-\sqrt{b} \mathcal{H}_{j}\left(\eta_{u}, \varphi ; \eta_{u}^{-}\right)\right| & =\left|\sum_{i=0}^{\ell-1} h_{j} \gamma_{i, 0} \varphi\left(x_{j+\frac{1}{2}}^{-}\right)+\left(w_{q, \ell}, \varphi\right)_{j}\right| \\
& \leq C h^{k+\ell+1}\|u\|_{k+\ell+2, \infty}\|\varphi\|_{1, I_{j}},
\end{aligned}
$$

where $\gamma_{0,0}=\bar{q}_{j, 0} \leq C h^{2 k+1}\|u\|_{k+2, \infty}$ owing to (3.4). This completes the proof of Lemma 3.3.

Remark 3.1 In contrast to the linear parabolic equations [6], $w_{u, i}$ and $w_{q, i}\left(i \in \mathbb{Z}_{k-1}\right)$ defined for nonlinear convection-diffusion equations in this paper are no longer orthogonal to $L_{j, 0}(x)$. Thus, the boundary terms containing $\beta_{i, 0}$ or $\gamma_{i, 0}$ will be generated. Fortunately, as shown in the proof of Lemma 3.3, these boundary terms are of high order and will not affect our superconvergence results.

Remark 3.2 If we choose the numerical fluxes (2.2b), we can define the following modified projection

$$
\stackrel{\circ}{\Pi}(u, q)=\left(P_{h}^{+} u, \dot{\mathbb{P}}_{h}^{-} q\right),
$$

in which $P_{h}^{+} u \in V_{h}^{k}$ has been given in (2.6b), and $\stackrel{\circ}{\mathbb{P}}_{h}^{-} q \in V_{h}^{k}$ depends on both $u$ and $q$ such that

$$
\begin{aligned}
& \int_{I_{j}}\left(q-\stackrel{\circ}{\mathbb{P}}_{h}^{-} q\right) v_{h} \mathrm{~d} x-\frac{1}{\sqrt{b}} \int_{I_{j}} f^{\prime}(u)\left(u-P_{h}^{+} u\right) v_{h} \mathrm{~d} x=0, \quad \forall v_{h} \in P^{k-1}\left(I_{j}\right), \\
& \stackrel{\circ}{\mathbb{P}}_{h}^{-} q\left(x_{j+\frac{1}{2}}^{-}\right)=q\left(x_{j+\frac{1}{2}}^{-}\right)-\frac{1}{\sqrt{b}} f^{\prime}(u)\left(u-P_{h}^{+} u\right)_{j+\frac{1}{2}}, \quad \forall j \in \mathbb{Z}_{N}^{+}
\end{aligned}
$$

We can see that $\stackrel{\circ}{\mathbb{P}}_{h}^{-}$is a generalized version of the local Gauss-Radau projection $P_{h}^{-}$. For this case, the correction functions $w_{u, i}, w_{q, i}$ are

$$
\begin{array}{ll}
\left(\sqrt{b} w_{u, i}-\bar{h}_{j} D_{x}^{-1} w_{q, i-1}, v\right)_{j}=0, & \left(w_{u, i}^{+}\right)_{j-\frac{1}{2}}=0, \\
\left(\sqrt{b} w_{q, i}-f^{\prime}(u) w_{u, i}-\bar{h}_{j} D_{x}^{-1} \partial_{t} w_{u, i-1}, v\right)_{j}=0, & \left(w_{q, i}^{-}\right)_{j+\frac{1}{2}}=\frac{1}{\sqrt{b}}\left(f^{\prime}(u) \widetilde{w}_{u, i}\right)_{j+\frac{1}{2}},
\end{array}
$$

where $v \in P^{k-1}\left(I_{j}\right)$, and

$$
w_{u, 0}=u-P_{h}^{+} u, \quad w_{q, 0}=q-\stackrel{\circ}{\mathbb{P}}_{h}^{-} q .
$$

By similar arguments as those used for fluxes (2.2a), we conclude that the results in Lemma 3.1-Lemma 3.3 are still valid for the fluxes (2.2b).

## 4 Superconvergence

In this section, we will prove the superconvergence properties for the LDG solution regarding cell averages and Radau points. To this end, let us first show a supercloseness result for $\left\|u_{I}^{\ell}-u_{h}\right\|$.

### 4.1 Supercloseness

To deal with the nonlinearity of the flux function $f(u)$, we should make an a priori assumption that for small enough $h$ there holds

$$
\begin{equation*}
\left\|P_{h}^{-} u-u_{h}\right\| \leq h^{2} . \tag{4.1}
\end{equation*}
$$

Note that this a priori assumption doesn't make sense when $k=0$. Therefore, all the following theorems only hold for $k \geq 1$.

## (i) Springer

Theorem 4.1 Let $u \in W^{k+\ell+3, \infty}, \ell \in \mathbb{Z}_{k}^{+}(k \geq 1)$ be the exact solution of the problem (1.1), and $u_{h}, q_{h}$ are the numerical solutions of $L D G$ scheme (2.1) satisfying (4.1). For periodic boundary conditions, if the initial discretization is chosen such that $u_{h}(\cdot, 0)=u_{I}^{\ell}(\cdot, 0)$, then

$$
\begin{equation*}
\left\|u_{I}^{\ell}-u_{h}\right\|+\left(\int_{0}^{t}\left\|q_{I}^{\ell}-q_{h}\right\|^{2} d \tau\right)^{\frac{1}{2}} \leq C h^{k+\ell+1} \tag{4.2}
\end{equation*}
$$

where $C$ depends on $t$ and $\|u\|_{k+\ell+3, \infty}$.
Proof Choosing $v=\xi_{u}, \varphi=\xi_{q}$ in the cell error equation (2.5), and summing up them over all cells, we obtain

$$
\begin{align*}
\frac{1}{2} \frac{\mathrm{~d}}{\mathrm{~d} t}\left\|\xi_{u}\right\|^{2}+\left\|\xi_{q}\right\|^{2}= & \left(-\left(\eta_{u}\right)_{t}, \xi_{u}\right)-\left(\eta_{q}, \xi_{q}\right)-\mathcal{H}\left(f(u)-f\left(u_{h}\right), \xi_{u} ; f(u)-\tilde{f}\left(u_{h}\right)\right) \\
& +\left.\sum_{j=1}^{N}\left(\tilde{f}\left(u_{h}\right)-\hat{f}\left(u_{h}\right)\right) \llbracket \xi_{u} \rrbracket\right|_{j+\frac{1}{2}}+\sqrt{b} \mathcal{H}\left(\eta_{q}, \xi_{u} ; \eta_{q}^{+}\right) \\
& +\sqrt{b} \mathcal{H}\left(\eta_{u}, \xi_{q} ; \eta_{u}^{-}\right) \\
& +\sqrt{b} \mathcal{H}\left(\xi_{q}, \xi_{u} ; \xi_{q}^{+}\right)+\sqrt{b} \mathcal{H}\left(\xi_{u}, \xi_{q} ; \xi_{u}^{-}\right) \tag{4.3}
\end{align*}
$$

where, for the nonlinear boundary terms, we have added and subtracted the "reference" function $\tilde{f}\left(u_{h}\right)$ defined by $(2.3)$ in $f(u)-\hat{f}\left(u_{h}\right)$. By using the second order Taylor expansion with respect to the variable $u$, we write out the nonlinear terms as follows

$$
\begin{align*}
& f(u)-f\left(u_{h}\right)=f^{\prime}(u) \xi_{u}+f^{\prime}(u) \eta_{u}-\frac{1}{2} \bar{f}_{u}^{\prime \prime}\left(\xi_{u}+\eta_{u}\right)^{2},  \tag{4.4a}\\
& f(u)-\tilde{f}\left(u_{h}\right)=f^{\prime}(u) \tilde{\xi}_{u}+f^{\prime}(u) \tilde{\eta}_{u}-\frac{1}{2} \bar{f}_{u}^{\prime \prime}\left(\tilde{\xi}_{u}+\tilde{\eta}_{u}\right)^{2}, \tag{4.4b}
\end{align*}
$$

where $\bar{f}_{u}^{\prime \prime}$ and $\overline{\bar{f}}_{u}^{\prime \prime}$ are the mean values, which can be given in the integral form of the remainder. Substituting (4.4) into (4.3), and using Lemma 3.3 in combination with the following skewsymmetry property

$$
\mathcal{H}\left(\xi_{q}, \xi_{u} ; \xi_{q}^{+}\right)+\mathcal{H}\left(\xi_{u}, \xi_{q} ; \xi_{u}^{-}\right)=0
$$

we get

$$
\begin{equation*}
\frac{1}{2} \frac{\mathrm{~d}}{\mathrm{~d} t}\left\|\xi_{u}\right\|^{2}+\left\|\xi_{q}\right\|^{2} \leq C h^{k+\ell+1}\left(\left\|\xi_{u}\right\|+\left\|\xi_{q}\right\|\right)+\Lambda+\Theta+\Psi \tag{4.5}
\end{equation*}
$$

where

$$
\begin{aligned}
& \Lambda=-\mathcal{H}\left(f^{\prime}(u) \xi_{u}, \xi_{u} ; f^{\prime}(u) \tilde{\xi}_{u}\right), \\
& \Theta=\frac{1}{2} \mathcal{H}\left(\bar{f}^{\prime \prime}(u) e_{u}^{2}, \xi_{u} ; \bar{f}^{\prime \prime}(u) \tilde{e}_{u}^{2}\right), \\
& \Psi=\left.\sum_{j=1}^{N}\left(\tilde{f}\left(u_{h}\right)-\hat{f}\left(u_{h}\right)\right) \llbracket \xi_{u} \rrbracket\right|_{j+\frac{1}{2}}
\end{aligned}
$$

will be estimated separately.

A simple integration by parts gives us the estimate for $\Lambda$; it reads,

$$
\begin{align*}
\Lambda & =-\frac{1}{2} \sum_{j=1}^{N} \int_{I_{j}} \partial_{x} f^{\prime}(u) \xi_{u}^{2} \mathrm{~d} x+\sum_{j=1}^{N}\left(f^{\prime}(u)\left(\tilde{\xi}_{u}-\left\{\left\{\xi_{u}\right\}\right\}\right) \llbracket \xi_{u} \rrbracket\right) \\
& \leq C\left\|\xi_{j}\right\|^{2}-\frac{1}{2} \\
& \leq C\left\|\xi_{j}\right\|^{2} . \tag{4.6a}
\end{align*}
$$

To deal with the high order term $\Theta$, let us first show a "rough" bound of order $k+1$ for $\|\xi\|_{\infty}$. It is easy to show that

$$
\begin{align*}
|\Theta| & \leq C h^{-1}\left\|e_{u}\right\|_{\infty}\left\|e_{u}\right\|\left\|\xi_{u}\right\|+C\left\|e_{u}\right\|_{\infty}\left(\left\|\xi_{u}\right\|_{\Gamma_{h}}+\left\|\eta_{u}\right\|_{\Gamma_{h}}\right)\left\|\xi_{u}\right\|_{\Gamma_{h}} \\
& \leq C h^{k}\left\|e_{u}\right\|_{\infty}\left\|\xi_{u}\right\|+C h^{-1}\left\|e_{u}\right\|_{\infty}\left\|\xi_{u}\right\|^{2}  \tag{4.6b}\\
& \leq\left(C h^{-1}\left\|e_{u}\right\|_{\infty}+C h^{-3}\left\|e_{u}\right\|_{\infty}^{2}\right)\left\|\xi_{u}\right\|^{2}+C h^{2 k+3}, \tag{4.6c}
\end{align*}
$$

where in the last step we have rewritten $h^{k}\left\|e_{u}\right\|_{\infty}\left\|\xi_{u}\right\|=h^{-\frac{3}{2}}\|e\|_{\infty}\left\|\xi_{u}\right\| h^{k+\frac{3}{2}}$ followed by the application of Young's inequality. For $\Psi$, using the Taylor expansion of $f$, the Cauchy-Schwarz inequality and the inverse inequality, we have the following estimate; see [4, Theorem 4.3]

$$
\begin{equation*}
|\Psi| \leq C h^{-2}\left\|e_{u}\right\|_{\infty}^{2}\left\|\eta_{u}\right\|_{\infty}^{2}+C\left(1+h^{-1}\left\|e_{u}\right\|_{\infty}\right)\left\|\xi_{u}\right\|^{2} \tag{4.6d}
\end{equation*}
$$

By the a priori error assumption (4.1), we have

$$
\begin{equation*}
\left\|e_{u}\right\|_{\infty} \leq\left\|u-P_{h}^{-} u\right\|_{\infty}+\left\|P_{h}^{-} u-u_{h}\right\|_{\infty} \leq C h^{\frac{3}{2}} . \tag{4.6e}
\end{equation*}
$$

Inserting the estimates (4.6a), (4.6c)-(4.6e) into (4.5), using Young's inequality and the Gronwall inequality, one has

$$
\left\|\xi_{u}\right\| \leq C h^{k+\frac{3}{2}} .
$$

Remark that the above estimate for $\left\|\xi_{u}\right\|$ is sufficient to verify the a priori error assumption (4.1) with $k \geq 1$; see, e.g., [22,24]. Then, we arrive at the following error estimate of order $k+1$ for $\left\|\xi_{u}\right\|_{\infty}$ and thus $\left\|e_{u}\right\|_{\infty}$.

$$
\begin{equation*}
\left\|e_{u}\right\|_{\infty} \leq\left\|\eta_{u}\right\|_{\infty}+h^{-\frac{1}{2}}\left\|\xi_{u}\right\| \leq C h^{k+1} . \tag{4.7}
\end{equation*}
$$

We are now ready to prove the supercloseness result in (4.2). Substituting (4.7) into (4.6b), (4.6d) and (4.5), and taking into account (4.6a), we obtain, after using Young's inequality

$$
\frac{1}{2} \frac{\mathrm{~d}}{\mathrm{~d} t}\left\|\xi_{u}\right\|^{2}+\left\|\xi_{q}\right\|^{2} \leq C h^{k+\ell+1}\left(\left\|\xi_{u}\right\|+\left\|\xi_{q}\right\|\right)+\left\|\xi_{u}\right\|^{2}+C h^{4 k+2}
$$

Choosing $u_{h}(\cdot, 0)=u_{I}^{\ell}(\cdot, 0)$ and using Gronwall inequality, we have

$$
\left\|\xi_{u}\right\|+\left(\int_{0}^{t}\left\|\xi_{q}\right\|^{2} \mathrm{~d} \tau\right)^{\frac{1}{2}} \leq C h^{k+\ell+1}
$$

This finishes the proof of Theorem 4.1.

## (4) Springer

### 4.2 Superconvergence

To derive superconvergence properties for the derivative approximation at Radau points, the following Lemma is needed.

Lemma 4.1 [2] Let $q_{h}, u_{h} \in V_{h}^{k}$ satisfy

$$
\left(q_{h}, \varphi\right)_{j}=\mathcal{H}_{j}\left(u_{h}, \varphi ; \hat{u}_{h}\right), \quad \forall \varphi \in V_{h}^{k}
$$

Then there holds for $\hat{u}_{h}=u_{h}^{-}$

$$
\partial_{x} u_{h}\left(\ell_{j, m}\right)=q_{h}\left(\ell_{j, m}\right), \quad(j, m) \in \mathbb{Z}_{N} \times \mathbb{Z}_{k},
$$

and for $\hat{u}_{h}=u_{h}^{+}$

$$
\partial_{x} u_{h}\left(r_{j, m}\right)=q_{h}\left(r_{j, m}\right), \quad(j, m) \in \mathbb{Z}_{N} \times \mathbb{Z}_{k}
$$

Due to the supercloseness result between $u_{I}^{\ell}$ and $u_{h}$ in Theorem 4.1, taking $\ell \leq k$ in the correction functions, we have the following superconvergence results for the LDG solution $u_{h}$.

Theorem 4.2 Assume that $u \in W^{2 k+3, \infty}(\Omega), k \geq 1$ is the solution of (1.1), and $u_{h}, q_{h}$ are the numerical solutions of the LDG scheme (1.1) when the alternating fluxes (2.2a) are used with the initial solution $u_{h}(\cdot, 0)=u_{I}^{k}(\cdot, 0)$. Then for periodic boundary conditions, we have the following superconvergence results
(1) Superconvergence of the numerical fluxes

$$
\left\|e_{u n}\right\|=\left(\frac{1}{N} \sum_{j=1}^{N}\left|\left(u-\hat{u}_{h}\right)\left(x_{j+\frac{1}{2}}, t\right)\right|^{2}\right)^{\frac{1}{2}} \leq C h^{2 k+1} .
$$

(2) Superconvergence for the cell averages

$$
\left\|e_{u}\right\|_{c}=\left(\frac{1}{N} \sum_{j=1}^{N}\left|\frac{1}{h_{j}} \int_{I_{j}}\left(u-u_{h}\right)(x, t) \mathrm{d} x\right|^{2}\right)^{\frac{1}{2}} \leq C h^{2 k+1} .
$$

(3) When $\ell \geq 2$, the function value approximation of the $L D G$ solution is $(k+2)$ th order superconvergent at right Radau points $r_{j, m}$, and the derivative value approximation is $(k+1)$ th order superconvergence at interior left Radau points (except the point $x=x_{j-\frac{1}{2}}$ ), i.e.,

$$
\begin{aligned}
& \left\|e_{u r}\right\|=\max _{j \in \mathbb{Z}_{N}}\left|\left(u-u_{h}\right)\left(r_{j, m}\right)\right| \leq C h^{k+2}, \\
& \left\|e_{u \ell}\right\|=\max _{j \in \mathbb{Z}_{N}}\left|\partial_{x}\left(u-u_{h}\right)\left(\ell_{j, m}\right)\right| \leq C h^{k+1} .
\end{aligned}
$$

It is worth pointing out that, when the direction of the flow doesn't change, the order of $\left\|e_{u \ell}\right\|$ can also be $k+2$.
(4) The numerical solution $\dot{u}_{h}$ is superconvergent with order $k+2$ towards the GaussRadau projection $P_{h}^{-} u$ of the exact solution, namely,

$$
\left\|u_{h}-P_{h}^{-} u\right\| \leq C h^{k+2} .
$$

The constant $C$ is independent of $h$.

Proof (1) It follows from the exact collocation of $P_{h}^{-}$in (2.6a) as well as $\left(w_{u, i}^{-}\right)_{j+\frac{1}{2}}=0$ in (3.10a), the inverse inequality and the supercloseness result in Theorem 4.1 that

$$
\begin{align*}
\left\|e_{u n}\right\| & =\left(\frac{1}{N} \sum_{j=1}^{N}\left|\left(u_{I}^{k}-u_{h}\right)\left(x_{j+\frac{1}{2}}, t\right)\right|^{2}\right)^{\frac{1}{2}} \\
& \leq\left(\frac{1}{N} \sum_{j=1}^{N} C h_{j}^{-1}\left\|u_{I}^{k}-u_{h}\right\|_{I_{j}}\right)^{\frac{1}{2}} \\
& \leq C\left\|u_{I}^{k}-u_{h}\right\| \leq C h^{2 k+1} . \tag{4.8}
\end{align*}
$$

(2) By the orthogonality property of $P_{h}^{-}$in (2.6a) and the definition of $u_{I}^{k}$, we obtain

$$
\left(e_{u}, 1\right)_{j}=\left(u_{I}^{k}-u_{h}, 1\right)_{j}+\left(W_{u}^{k}, 1\right)_{j} .
$$

Then, by a direct calculation and taking into account (3.13a) with $m=0$ due to the orthogonality property of Legendre polynomials, we get

$$
\left\|e_{u}\right\|_{c} \leq\left\|u_{I}^{k}-u_{h}\right\|+C h^{2 k+1}\|u\|_{2 k+3, \infty} \leq C h^{2 k+1}
$$

(3) If we take $\ell \geq 2$ in Theorem 4.1, and use the inverse inequality, we obtain

$$
\left\|\xi_{u}\right\|_{\infty} \leq C h^{k+\frac{5}{2}} .
$$

By the triangle inequality,

$$
\begin{aligned}
\left|\left(u-u_{h}\right)\left(r_{j, m}\right)\right| & \leq\left|\left(u-P_{h}^{-} u\right)\left(r_{j, m}\right)\right|+\left\|\xi_{u}\right\|_{\infty}+\left\|W_{u}^{\ell}\right\|_{\infty} \\
& \leq C h^{k+2},
\end{aligned}
$$

where we have also used $\left|\left(u-P_{h}^{-} u\right)\left(r_{j, m}\right)\right| \leq C h^{k+2}$ due to the standard approximation theory. The result of the other equation for the derivative approximations can be obtained by the same arguments.

Moreover, if the direction of the flow doesn't change, combining Lemma 3.1, Lemma 3.2 and Lemma 4.1 we have

$$
\left|\partial_{x}\left(u-u_{h}\right)\left(\ell_{j, m}\right)\right|=\left|\left(q-q_{h}\right)\left(\ell_{j, m}\right)\right| \leq C h^{k+2} .
$$

(4) Using the triangle inequality,

$$
\left\|u_{h}-P_{h}^{-} u\right\| \leq\left\|P_{h}^{-} u-W_{u}^{k}-u_{h}\right\|+\left\|W_{u}^{k}\right\| \leq C h^{k+2} .
$$

This finishes the proof of Theorem 4.2.
Remark 4.1 From the construction of the special projection in (3.1), we can see that the conclusion is only valid for $b=\mathcal{O}(1)$. For convection dominated problems with small diffusion coefficient $b \ll 1$, the exact solution often exists a boundary layer near the outflow boundary. When the direction of the flow doesn't change, we can observe superconvergence property similar to the nonlinear hyperbolic equations [4] out of the local subdomain with pollution width of $\mathcal{O}(h \ln N)$.

Remark 4.2 For the strongly anisotropic problems when $b$ is very large, the theoretical results are still valid, since $\Phi=(-1)^{k} \frac{1}{\sqrt{b}} f^{\prime}(u)\left(u \widetilde{P_{h}^{-}} u\right)_{j-\frac{1}{2}}$ has an additional order $\frac{1}{\sqrt{b}}$. However, this case requires a smaller time step when explicit time discretization methods are used.

## (i) Springer

Remark 4.3 For high dimensions, we need to introduce more auxiliary variables, such as $p=u_{x}, q=u_{y}$ for the two-dimensional case. Unfortunately, it is difficult to construct an interpolation function to deal with $p=u_{x}$ and $q=u_{y}$ simultaneously. The main technical difficulty is that the conditions they need to satisfy are interactive restricted in the process of constructing interpolation functions.

### 4.3 The Initial Discretization

In this section, we consider how to discretize the initial datum. Initial value discretization is very important for the study of superconvergence, which can be obtained using the same technique as that in [2]. Specifically, for periodic boundary conditions,

1. according to the definition of projection $P_{h}^{-}, \mathbb{P}_{h}^{+}$, calculate the $w_{u, 0}, w_{q, 0}$;
2. calculate $w_{u, i}, w_{q, i}$ by the equations (3.10);
3. calculate $W_{u}^{\ell}=\sum_{i=1}^{\ell} w_{u, i}, u_{I}^{\ell}=P_{h}^{-} u-W_{u}^{\ell}$;
4. let $u_{h}(\cdot, 0)=u_{I}^{\ell}(\cdot, 0)$.

## 5 Extensions

### 5.1 Generalized Alternating Numerical Fluxes

In this section, we extend the superconvergence results to generalized alternating numerical fluxes. To be more specific, the numerical fluxes can be in the following form

$$
\hat{v}_{j+\frac{1}{2}}=v_{j+\frac{1}{2}}^{(\theta)}=\theta v_{j+\frac{1}{2}}^{-}+\tilde{\theta} v_{j+\frac{1}{2}}^{+}, \quad \tilde{\theta}=1-\theta .
$$

When the numerical fluxes $\left(u_{h}^{(\theta)}, q_{h}^{(\tilde{\theta})}\right)$ are used, we introduce a modified projection $\widetilde{\Pi}(u, q)=\left(P_{\theta} u, \mathbb{P}_{\tilde{\theta}} q\right)$ satisfying

$$
\begin{array}{ll}
\int_{I_{j}}\left(P_{\theta} u-u\right) v_{h} \mathrm{~d} x=0, & \forall v_{h} \in P^{k-1}\left(I_{j}\right), \\
\left(P_{\theta} u\right)_{j+\frac{1}{2}}^{(\theta)}=u_{j+\frac{1}{2}}^{(\theta)}, & \forall j \in \mathbb{Z}_{N}^{+},
\end{array}
$$

and $\mathbb{P}_{\tilde{\theta}} q \in V_{h}^{k}$ depends on both $u$ and $q$ such that

$$
\begin{array}{ll}
\int_{I_{j}}\left(q-\mathbb{P}_{\tilde{\theta}} q\right) v_{h} \mathrm{~d} x-\frac{1}{\sqrt{b}} \int_{I_{j}} f^{\prime}(u)\left(u-P_{\theta} u\right) v_{h} \mathrm{~d} x=0, & \forall v_{h} \in P^{k-1}\left(I_{j}\right), \\
\left(\mathbb{P}_{\tilde{\theta}} q\right)_{j+\frac{1}{2}}^{(\tilde{\theta})}=q_{j+\frac{1}{2}}^{(\tilde{\theta})}-\frac{1}{\sqrt{b}} f^{\prime}\left(u_{j+\frac{1}{2}}\right)\left(\widetilde{\left(u-P_{\theta} u\right)_{j+\frac{1}{2}},}\right. & \forall j \in \mathbb{Z}_{N}^{+}
\end{array}
$$

Similar to (3.2), the boundary terms of the projection errors for both convection and diffusion parts can be eliminated. For more properties of global projections; see, e.g., [11,21].

Analogously, we define a series of functions $w_{u, i}, w_{q, i}, i \in \mathbb{Z}_{k}^{+}$as follows

$$
\begin{array}{ll}
\left(\sqrt{b} w_{u, i}-\bar{h}_{j} D_{x}^{-1} w_{q, i-1}, v_{h}\right)_{j}=0, & \left(w_{u, i}^{(\theta)}\right)_{j+\frac{1}{2}}=0, \\
\left(\sqrt{b} w_{q, i}-w_{u, i}-\bar{h}_{j} D_{x}^{-1} \partial_{t} w_{u, i-1}, v_{h}\right)_{j}=0, & \left(w_{q, i}^{(\tilde{\theta})}\right)_{j+\frac{1}{2}}=\frac{1}{\sqrt{b}} f^{\prime}\left(u_{j+\frac{1}{2}}\right)\left(\widetilde{w}_{u, i}\right)_{j+\frac{1}{2}}
\end{array}
$$

where $v_{h} \in P^{k-1}\left(I_{j}\right)$, and

$$
w_{u, 0}=u-P_{\theta} u, \quad w_{q, 0}=q-\mathbb{P}_{\tilde{\theta}} q .
$$

Following the same argument as that in Sect. 3, we can obtain superconvergence results similar to Lemmas 3.1-3.3. The main difference is that we need to solve linear coupled systems involving the coefficients $\bar{q}_{j, k}, \beta_{i, k}$, and $\gamma_{i, k}$ for $j \in \mathbb{Z}_{N}^{+}$.

Next, let us present some preliminary results related to the superconvergence results based on generalized alternating numerical fluxes. The generalized Radau polynomials are defined as in [3]

$$
R_{k+1}^{\theta}= \begin{cases}L_{k+1}-(2 \theta-1) L_{k}, & \text { when } k \text { is even } \\ (2 \theta-1) L_{k+1}-L_{k}, & \text { when } k \text { is odd }\end{cases}
$$

For any positive $\theta \neq \frac{1}{2}, j \in \mathbb{Z}_{N}^{+}$, if the following local projection $P_{h} u \in V_{h}^{k}$ in [3] is introduced,

$$
\begin{aligned}
\int_{I_{j}}\left(P_{h} u-u\right) v \mathrm{~d} x & =0, \quad \forall v \in P^{k-1}\left(I_{j}\right), \\
\theta P_{h} u\left(x_{j+\frac{1}{2}}^{-}\right)+(1-\theta) P_{h} u\left(x_{j-\frac{1}{2}}^{+}\right) & =\theta u\left(x_{j+\frac{1}{2}}^{-}\right)+(1-\theta) u\left(x_{j-\frac{1}{2}}^{+}\right) .
\end{aligned}
$$

Then the following superconvergence results hold.
Lemma 5.1 [3] Suppose $u \in W^{k+2, \infty}(\Omega)$ and $P_{h} u$ is the local projection of $u$ defined above with $\theta \neq \frac{1}{2}$, then

$$
\begin{aligned}
& \left|\left(u-P_{h} u\right)\left(\mathcal{R}_{j, m}\right)\right| \leq C h^{k+2}, \\
& \left|\partial_{x}\left(u-P_{h} u\right)\left(\mathcal{R}_{j, m}^{\star}\right)\right| \leq C h^{k+1}, \\
& \left\|P_{h} u-P_{\theta} u\right\|_{\infty} \leq C h^{k+2} .
\end{aligned}
$$

Here $\mathcal{R}_{j, m}, \mathcal{R}_{j, m}^{\star}$ are the roots of $R_{j, m+1}^{\theta}$ and $\partial_{x} R_{j, m+1}^{\theta}$, and $C$ is independent of $h$.
Following the same argument as what we did in Sect. 4, we obtain the superconvergence results based on generalized alternating numerical fluxes, whose detailed proofs are omitted to save space.

Theorem 5.1 Assume that $u \in W^{2 k+3, \infty}(\Omega), k \geq 1$ is the solution of (1.1), and $u_{h}, q_{h}$ are the numerical solutions of LDG scheme (1.1) when the numerical fluxes $\left(u_{h}^{(\theta)}, q_{h}^{(\tilde{\theta})}\right.$ ) are used with the initial solution $u_{h}(\cdot, 0)=u_{I}^{k}(\cdot, 0)$. Then for periodic boundary conditions, we have the following superconvergence results

1. Superconvergence of the numerical flux

$$
\left\|e_{u n}\right\|=\left(\frac{1}{N} \sum_{j=1}^{N}\left|\left(u-u_{h}\right)^{(\theta)}\left(x_{j+\frac{1}{2}}, t\right)\right|^{2}\right)^{\frac{1}{2}} \leq C h^{2 k+1}
$$

## (4) Springer

2. Superconvergence for the cell averages

$$
\left\|e_{u}\right\|_{c}=\left(\frac{1}{N} \sum_{j=1}^{N}\left|\frac{1}{h_{j}} \int_{I_{j}}\left(u-u_{h}\right)(x, t) \mathrm{d} x\right|^{2}\right)^{\frac{1}{2}} \leq C h^{2 k+1} .
$$

3. When $\ell \geq 2$, the function value approximation of the LDG solution is $(k+2)$ th order superconvergent at interior generalized Radau points $\mathcal{R}_{j, m}$, and the derivative value approximation is $(k+1)$ th order superconvergence at interior generalized derivative Radau points $\mathcal{R}_{j, m}^{\star}$, i.e.,

$$
\begin{aligned}
& \left\|e_{u r}\right\|=\max _{j \in \mathbb{Z}_{N}}\left|\left(u-u_{h}\right)\left(\mathcal{R}_{j, m}\right)\right| \leq C h^{k+2}, \\
& \left\|e_{u r}^{\star}\right\|=\max _{j \in \mathbb{Z}_{N}}\left|\partial_{x}\left(u-u_{h}\right)\left(\mathcal{R}_{j, m}^{\star}\right)\right| \leq C h^{k+1} .
\end{aligned}
$$

4. The numerical solution $u_{h}$ is superconvergent with order $k+2$ towards the global projection $P_{\theta} u$ of the exact solution, namely,

$$
\left\|u_{h}-P_{\theta} u\right\| \leq C h^{k+2} .
$$

The constant $C$ is independent of $h$.

### 5.2 Mixed Boundary Conditions

Consider the following mixed boundary conditions

$$
\begin{equation*}
u(0, t)=g_{1}(t), \quad u_{x}(2 \pi, t)=g_{2}(t) . \tag{5.2}
\end{equation*}
$$

For simplicity, we choose the numerical fluxes as

$$
\left(\hat{f}\left(u_{h}\right), \hat{u}_{h}, \hat{q}_{h}\right)_{j+\frac{1}{2}}= \begin{cases}\left(f\left(g_{1}\right), g_{1}, q_{h}^{+}\right)_{\frac{1}{2}}, & j=0,  \tag{5.3}\\ \left(\text { Godunov flux, } u_{h}^{-}, q_{h}^{+}\right)_{j+\frac{1}{2}}, & j=1, \ldots, N-1, \\ \left(f\left(u_{h}^{-}\right), u_{h}^{-}, g_{2}\right)_{N+\frac{1}{2}}, & j=N .\end{cases}
$$

The projection $\mathbb{P}_{h}^{+}$defined in (3.1) is modified to $\tilde{\mathbb{P}}_{h}^{+}$determined by

$$
\begin{array}{ll}
\int_{I_{j}}\left(q-\tilde{\mathbb{P}}_{h}^{+} q\right) v_{h} \mathrm{~d} x-\frac{1}{\sqrt{b}} \int_{I_{j}} f^{\prime}(u)\left(u-P_{h}^{-} u\right) v_{h} \mathrm{~d} x=0, & \forall v_{h} \in P^{k-1}\left(I_{j}\right), \\
\tilde{\mathbb{P}}_{h}^{+} q\left(x_{j-\frac{1}{2}}^{+}\right)=q\left(x_{j-\frac{1}{2}}^{+}\right)-\frac{1}{\sqrt{b}} f^{\prime}(u)\left(u-P_{h}^{-} u\right)_{j-\frac{1}{2}}, & \forall j \in \mathbb{Z}_{N}^{+} \backslash\{1\}, \\
\tilde{\mathbb{P}}_{h}^{+} q\left(x_{\frac{1}{2}}^{+}\right)=q\left(x_{\frac{1}{2}}^{+}\right),
\end{array}
$$

where $\widetilde{w}$ has been defined in (2.3). Then we construct the following correction functions

$$
\begin{array}{lll}
\left(w_{u, i}-\bar{h}_{j} D_{x}^{-1} w_{q, i-1}, z\right)_{j}=0, & \left(w_{u, i}^{-}\right)_{j+\frac{1}{2}}=0, & \forall j \in \mathbb{Z}_{N}^{+}, \\
\left(w_{q, i}-w_{u, i}-\bar{h}_{j} D_{x}^{-1} \partial_{t} w_{u, i-1}, z\right)_{j}=0, & \left(w_{q, i}^{+}\right)_{j-\frac{1}{2}}=\left.\frac{1}{\sqrt{b}} f^{\prime}(u) \widetilde{w}_{u, i}\right|_{j-\frac{1}{2}}, & \forall j \in \mathbb{Z}_{N}^{+} \backslash\{1\}, \\
& \left(w_{q, i}^{+}\right)_{\frac{1}{2}}=0 &
\end{array}
$$

for $\forall z \in P^{k-1}\left(I_{j}\right)$. The superconvergence results can thus be obtained if we follow the same arguments as those in Sects. 3 and 4.

Remark 5.1 The novelty in designing a new projection is that the diffusion term is used to balance the convection term. Therefore, when constructing $\Pi(u, q)$ in Sect. 3.1, the projection $P_{h}^{-}$dealing with convection term should be designed first, and then the projection $\mathbb{P}_{h}^{+}$. For the case of Dirichlet boundary conditions

$$
u(0, t)=g_{3}(t), \quad u(2 \pi, t)=g_{4}(t),
$$

it is difficult to modify the projection $\mathbb{P}_{h}^{+}$to eliminate the boundary term introduced by the auxiliary variable $q$. However, the superconvergence phenomenon can still be obseryed when we follow [13] and define the numerical fluxes as follows

$$
\left(\hat{f}\left(u_{h}\right), \hat{u}_{h}, \hat{q}_{h}\right)_{j+\frac{1}{2}}= \begin{cases}\left(f\left(g_{3}\right), g_{3}, q_{h}^{+}\right)_{\frac{1}{2}}, & j=0, \\ \left(\text { Godunov flux, } u_{h}^{-}, q_{h}^{+}\right)_{j+\frac{1}{2}}, & j=1, \ldots, N-1,(5.4) \\ \left(f\left(u_{h}^{-}\right)-\kappa\left(g_{4}-u_{h}^{-}\right), g_{4}, q_{h}^{-}\right)_{N+\frac{1}{2}}, & j=N,\end{cases}
$$

where $\kappa=\mathcal{O}\left(h^{-1}\right)$ is a positive constant. See Table 8 for numerical results.

### 5.3 Superconvergence for the Auxiliary Variable

For the numerical flux in (2.2a), the superconvergence properties still hold for the auxiliary variable $q$, if the direction of the flow doesn't change.

Theorem 5.2 Assume that $u \in W^{2 k+3, \infty}(\Omega), k \geq 1$ is the solution of (1.1), and $u_{h}, q_{h}$ are the numerical solutions of LDG scheme (1.1) when the alternating fluxes (2.2a) are used with the initial solution $u_{h}(\cdot, 0)=u_{I}^{k}(\cdot, 0)$. Then for periodic boundary conditions, we have the following superconvergence results for the auxiliary variable $q_{h}$.

1. Superconvergence of the numerical flux

$$
\left(\int_{0}^{t}\left\|e_{q n}\right\|^{2} \mathrm{~d} \tau\right)^{\frac{1}{2}} \leq C h^{2 k+1} .
$$

2. Superconvergence for the cell averages

$$
\left(\int_{0}^{t}\left\|e_{q}\right\|_{c}^{2} \mathrm{~d} \tau\right)^{\frac{1}{2}} \leq C h^{2 k+1}
$$

3. When $\ell \geq 2$, the function value approximation of the $L D G$ solution is $(k+2)$ th order superconvergent at left Radau points $\ell_{j, m}$, and the derivative value approximation is $(k+1)$ th order superconvergence at the interior right Radau points, except the point $x=x_{j+\frac{1}{2}}$, i.e.,

$$
\left(\int_{0}^{t}\left\|e_{q \ell}\right\|^{2} \mathrm{~d} \tau\right)^{\frac{1}{2}} \leq C h^{k+2}, \quad\left(\int_{0}^{t}\left\|e_{q r}\right\|^{2} \mathrm{~d} \tau\right)^{\frac{1}{2}} \leq C h^{k+1} .
$$

4. The numerical solution $q_{h}$ is superconvergent with order $k+2$ towards the Gauss-Radau projection $P_{h}^{+} q$ of the exact solution, namely,

$$
\left(\int_{0}^{t}\left\|q_{h}-P_{h}^{+} q\right\|^{2} \mathrm{~d} \tau\right)^{\frac{1}{2}} \leq C h^{k+2} .
$$

The norms aforementioned can be defined as the same way as in Theorem 4.2 and $C$ is independent of $h$.

## (4) Springer

Table 1 CFL constants for different numerical examples

|  | Table 2 | Table 3 | Table 4 | Table 5 | Table 6 | Table 7 | Table 8 | Table 9 |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| $C F L_{1}$ | 0.02 | 0.02 | 0.02 | 0.02 | 0.005 | 0.0005 | 0.02 | 0.1 |
| $C F L_{2}$ | 0.01 | 0.005 | 0.01 | 0.005 | 0.003 | 0.0001 | 0.01 | 0.1 |
| $C F L_{3}$ | 0.002 | 0.002 | 0.005 | 0.002 | 0.001 | - | - | - |

Remark 5.2 In the superconvergence analysis, the correction functions ( $W_{u}^{\ell}, W_{q}^{\ell}$ ) we designed should satisfy the following properties

$$
\left(W_{u}^{\ell}\right)_{j+\frac{1}{2}}^{-}=0, \quad\left(W_{q}^{\ell}\right)_{j-\frac{1}{2}}^{+}=0, \quad j \in \mathbb{Z}_{N},
$$

which are needed to derive superconvergence of the numerical flux in (4.8). Therefore, it is easy to see that superconvergence of the auxiliary variable $q_{h}$ is no longer valid when the flow direction changes in (3.10b), or the generalized alternating numerical fluxes (5.1b) are used. The superconvergence can be observed numerically in the $L^{\infty}\left([0, T] ; L^{2}(\Omega)\right)$ norm.

## 6 Numerical Experiments

In this section, we provide numerical examples to verify our theoretical results. For time discretization, we use the third order explicit total variation diminishing Runge-Kutta method and take $\Delta t=C F L_{k} * h^{2}$ for $P^{k}(1 \leq k \leq 3)$ polynomials. In all examples, uniform meshes are considered and the parameters $C F L_{k}$ are listed in Table 1.

Example 6.1 We first consider the following problem with the direction of the flow not change

$$
\begin{array}{ll}
u_{t}+\left(e^{u}\right)_{x}-b u_{x x}=g(x, t), \\
u(x, 0)=\sin (5 x), & (x, t) \in[0,2 \pi] \times(0, T], \\
x \in[0,2 \pi]
\end{array}
$$

with the periodic boundary condition. $g(x, t)$ is suitably chosen such that the exact solution is

$$
u(x, t)=e^{-b t} \sin (5 x+t)
$$

Table 2 lists results for $u$ and $q$ when $b=1.2, T=1$, from which we observe $(2 k+1)$ th order superconvergence for the numerical trace as well as cell averages. In addition, for the prime variable $u_{h}$, superconvergence of the function value approximation and the derivative approximation at Radau points both achieve $(k+2)$ th order. In Table 3, we present the $L^{2}$ errors of $\xi_{u}, \xi_{q}, P_{h}^{+} q-q_{h}$ and $P_{h}^{-} u-u_{h}$, which demonstrates that the LDG solution $u_{h}\left(q_{h}\right)$ is superconvergent with order $k+2$ towards the Gauss-Radau projection $P_{h}^{-} u\left(P_{h}^{+} q\right)$. Moreover, by correcting the local projection, the order of $L^{2}$ error between numerical solution and interpolation function can reach $2 k+1$.

Example 6.2 In this example, we consider the following problem with the direction of the flow changes

$$
\begin{array}{ll}
u_{t}+\left(u^{2} / 2\right)_{x}-b u_{x x}=g(x, t), & (x, t) \in[0,2 \pi] \times(0, T], \\
u(x, 0)=\sin (3 x), & x \in[0,2 \pi]
\end{array}
$$

Table 2 Errors and rates for Example 6.1 with $b=1.2, T=1$

|  | $N$ | $\left\\|e_{u n}\right\\|$ | Rate | $\left\\|e_{u}\right\\|_{c}$ | Rate | $\left\\|e_{u r}\right\\|$ | Rate | $\left\\|e_{u \ell}\right\\|$ | Rate |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $P^{1}$ | 40 | $2.54 \mathrm{E}-04$ | - | $1.36 \mathrm{E}-03$ | - | $1.62 \mathrm{E}-03$ | - | $5.06 \mathrm{E}-03$ | - |
|  | 80 | $3.17 \mathrm{E}-05$ | 3.00 | $1.73 \mathrm{E}-04$ | 2.97 | $2.17 \mathrm{E}-04$ | 2.90 | $6.32 \mathrm{E}-04$ | 3.00 |
|  | 160 | $3.97 \mathrm{E}-06$ | 2.99 | $2.18 \mathrm{E}-05$ | 2.99 | $2.78 \mathrm{E}-05$ | 2.96 | $8.09 \mathrm{E}-05$ | 2.97 |
|  | 320 | $4.97 \mathrm{E}-07$ | 3.00 | $2.73 \mathrm{E}-06$ | 3.00 | $3.51 \mathrm{E}-06$ | 2.98 | $1.02 \mathrm{E}-05$ | 2.99 |
| $P^{2}$ | 20 | $1.28 \mathrm{E}-04$ | - | $1.47 \mathrm{E}-04$ | - | $8.28 \mathrm{E}-04$ | - | $3.57 \mathrm{E}-03$ | - |
|  | 40 | $3.95 \mathrm{E}-06$ | 5.01 | $4.51 \mathrm{E}-06$ | 5.02 | $4.60 \mathrm{E}-05$ | 4.17 | $2.20 \mathrm{E}-04$ | 4.02 |
|  | 80 | $1.20 \mathrm{E}-07$ | 5.03 | $1.38 \mathrm{E}-07$ | 5.03 | $2.84 \mathrm{E}-06$ | 4.02 | $1.49 \mathrm{E}-05$ | 3.88 |
|  | 160 | $3.66 \mathrm{E}-09$ | 5.04 | $4.24 \mathrm{E}-09$ | 5.03 | $1.72 \mathrm{E}-07$ | 4.04 | $9.50 \mathrm{E}-07$ | 3.97 |
| $P^{3}$ | 30 | $1.04 \mathrm{E}-07$ | - | $1.15 \mathrm{E}-07$ | - | $4.37 \mathrm{E}-06$ |  | $3.25 \mathrm{E}-05$ | - |
|  | 40 | $1.32 \mathrm{E}-08$ | 7.15 | $1.47 \mathrm{E}-08$ | 7.15 | $1.01 \mathrm{E}-06$ | 5.10 | $8.58 \mathrm{E}-06$ | 4.62 |
|  | 50 | $2.74 \mathrm{E}-09$ | 7.05 | $3.04 \mathrm{E}-09$ | 7.05 | $3.46 \mathrm{E}-07$ | 4.78 | $2.81 \mathrm{E}-06$ | 4.99 |
|  | 60 | $7.56 \mathrm{E}-10$ | 7.06 | 8.37E-10 | 7.06 | $1.40 \mathrm{E}-07$ | 4.98 | $1.10 \mathrm{E}-06$ | 5.13 |
|  | $N$ | $\left\\|e_{q n}\right\\|$ | Rate | $\left\\|e_{q}\right\\|_{c}$ | Rate | $\left\\|e_{q r}\right\\|$ | Rate | $\left\\|e_{q \ell}\right\\|$ | Rate |
| $P^{1}$ | 40 | $2.67 \mathrm{E}-04$ | - | $1.38 \mathrm{E}-03$ | - | $1.36 \mathrm{E}-01$ | - | $5.54 \mathrm{E}-03$ | - |
|  | 80 | $3.35 \mathrm{E}-05$ | 2.99 | $1.77 \mathrm{E}-04$ | 2.96 | $3.52 \mathrm{E}-02$ | 1.96 | $6.92 \mathrm{E}-04$ | 3.00 |
|  | 160 | $4.20 \mathrm{E}-06$ | 2.99 | $2.23 \mathrm{E}-05$ | 2.98 | $8.82 \mathrm{E}-03$ | 1.99 | $8.86 \mathrm{E}-05$ | 2.96 |
|  | 320 | $5.26 \mathrm{E}-07$ | 3.00 | $2.80 \mathrm{E}-06$ | 2.99 | $2.20 \mathrm{E}-03$ | 2.00 | $1.11 \mathrm{E}-05$ | 2.99 |
| $P^{2}$ | 20 | $1.26 \mathrm{E}-05$ | - | $9.42 \mathrm{E}-05$ | - | $1.02 \mathrm{E}-01$ | - | $3.91 \mathrm{E}-03$ | - |
|  | 40 | $4.70 \mathrm{E}-07$ | 4.75 | $3.30 \mathrm{E}-06$ | 4.83 | $1.25 \mathrm{E}-02$ | 3.03 | $2.41 \mathrm{E}-04$ | 4.02 |
|  | 80 | $1.48 \mathrm{E}-08$ | 4.98 | $1.04 \mathrm{E}-07$ | 4.98 | $1.65 \mathrm{E}-03$ | 2.92 | $1.63 \mathrm{E}-05$ | 3.88 |
|  | 160 | $4.63 \mathrm{E}-10$ | 5.00 | $3.26 \mathrm{E}-09$ | 5.00 | $2.07 \mathrm{E}-04$ | 2.99 | $1.04 \mathrm{E}-06$ | 3.97 |
| $P^{3}$ | 30 | $1.67 \mathrm{E}-08$ | - | $6.61 \mathrm{E}-08$ |  | $2.18 \mathrm{E}-03$ | - | $3.56 \mathrm{E}-05$ | - |
|  | 40 | $2.07 \mathrm{E}-09$ | 7.25 | $9.94 \mathrm{E}-09$ | 6.58 | $6.86 \mathrm{E}-04$ | 4.03 | $9.40 \mathrm{E}-06$ | 4.63 |
|  | 50 | $4.26 \mathrm{E}-10$ | 7.09 | $2.10 \mathrm{E}-09$ | 6.97 | $2.97 \mathrm{E}-04$ | 3.75 | $3.08 \mathrm{E}-06$ | 4.99 |
|  | 60 | $1.16 \mathrm{E}-10$ | 7.13 | $5.86 \mathrm{E}-10$ | 6.99 | $1.43 \mathrm{E}-04$ | 4.02 | $1.21 \mathrm{E}-06$ | 5.13 |

with the periodic boundary condition. The source term $g(x, t)$ is specially chosen such that the exact solution is

$$
u(x, t)=e^{-b t} \sin (3 x+t) .
$$

We list various errors and corresponding convergence rates when $b=1.0, T=1$ in Table 4. Superconvergence of order $2 k+1$ for the numerical trace as well as cell averages, and $(k+2)$ th order of the function value approximation at Radau points confirm the sharpness of Theorem 4.2 when the flow direction does change its sign. Moreover, the derivative approximation at Radau points achieves $(k+1)$ th order as expected. In addition, superconvergence results for $\xi_{u}$ and $P_{h}^{-} u-u_{h}$ in the $L^{2}$ norm are shown in Table 5, for $b=0.1, b=2.0$. For this problem, results of the generalized alternating fluxes with different weights $\theta$ with $b=2.0$ are shown in Table 6, demonstrating that superconvergence results are still valid for the generalized numerical fluxes in Sect. 5.1.

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Table 3 Errors and rates for Example 6.1 with $b=2.0, T=1$

|  | $N$ | $\left\\|\xi_{u}\right\\|$ | Rate | $\left\\|P_{h}^{-} u-u_{h}\right\\|$ | Rate | $\left\\|\xi_{q}\right\\|$ | Rate | $\left\\|P_{h}^{+} q-q_{h}\right\\|$ | Rate |
| ---: | ---: | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| $P^{1}$ | 40 | $1.64 \mathrm{E}-04$ | - | $1.79 \mathrm{E}-03$ | - | $1.18 \mathrm{E}-03$ | - | $1.27 \mathrm{E}-03$ | - |
|  | 80 | $2.06 \mathrm{E}-05$ | 2.99 | $2.29 \mathrm{E}-04$ | 2.97 | $1.54 \mathrm{E}-04$ | 2.93 | $1.64 \mathrm{E}-04$ | 2.96 |
|  | 160 | $2.60 \mathrm{E}-06$ | 2.98 | $2.88 \mathrm{E}-05$ | 2.99 | $1.97 \mathrm{E}-05$ | 2.97 | $2.07 \mathrm{E}-05$ | 2.98 |
|  | 320 | $3.27 \mathrm{E}-07$ | 2.99 | $3.61 \mathrm{E}-06$ | 2.99 | $2.48 \mathrm{E}-06$ | 2.98 | $2.61 \mathrm{E}-06$ | 2.99 |
| $P^{2}$ | 20 | $1.81 \mathrm{E}-04$ | - | $8.63 \mathrm{E}-04$ | - | $3.21 \mathrm{E}-05$ | - | $5.72 \mathrm{E}-04$ | - |
|  | 40 | $5.97 \mathrm{E}-06$ | 4.92 | $5.49 \mathrm{E}-05$ | 3.97 | $1.06 \mathrm{E}-06$ | 4.92 | $3.56 \mathrm{E}-05$ | 4.00 |
|  | 80 | $1.87 \mathrm{E}-07$ | 5.00 | $3.45 \mathrm{E}-06$ | 3.99 | $3.16 \mathrm{E}-08$ | 5.06 | $2.24 \mathrm{E}-06$ | 3.99 |
|  | 160 | $5.77 \mathrm{E}-09$ | 5.02 | $2.16 \mathrm{E}-07$ | 3.99 | $9.68 \mathrm{E}-10$ | 5.03 | $1.41 \mathrm{E}-07$ | 3.99 |
| $P^{3}$ | 30 | $1.46 \mathrm{E}-07$ | - | $7.35 \mathrm{E}-06$ | - | $1.51 \mathrm{E}-08$ | - | $4.96 \mathrm{E}-06$ | - |
|  | 40 | $1.95 \mathrm{E}-08$ | 6.98 | $1.76 \mathrm{E}-06$ | 4.97 | $1.82 \mathrm{E}-09$ | 7.34 | $1.18 \mathrm{E}-06$ | 4.98 |
|  | 50 | $4.12 \mathrm{E}-09$ | 6.97 | $5.79 \mathrm{E}-07$ | 4.98 | $3.65 \mathrm{E}-10$ | 7.19 | $3.90 \mathrm{E}-07$ | 4.98 |
|  | 60 | $1.15 \mathrm{E}-09$ | 7.00 | $2.33 \mathrm{E}-07$ | 4.99 | $9.84 \mathrm{E}-11$ | 7.19 | $1.57 \mathrm{E}-07$ | 4.99 |

Table 4 Errors and rates for Example 6.2 with $b=1.0, T=1$

|  | $N$ | $\left\\|e_{u n}\right\\|$ | Rate | $\left\\|e_{u}\right\\|_{c}$ | Rate | $\left\\|e_{u r}\right\\|$ | Rate | $\left\\|e_{u \ell}\right\\|$ | Rate |
| ---: | ---: | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| $P^{1}$ | 40 | $2.00 \mathrm{E}-04$ | - | $4.56 \mathrm{E}-04$ | - | $7.32 \mathrm{E}-04$ | - | $2.38 \mathrm{E}-03$ | - |
|  | 80 | $2.61 \mathrm{E}-05$ | 2.94 | $5.79 \mathrm{E}-05$ | 2.98 | $9.28 \mathrm{E}-05$ | 2.98 | $5.07 \mathrm{E}-04$ | 2.23 |
|  | 160 | $3.30 \mathrm{E}-06$ | 2.98 | $7.26 \mathrm{E}-06$ | 2.99 | $1.16 \mathrm{E}-05$ | 3.00 | $1.16 \mathrm{E}-04$ | 2.13 |
|  | 320 | $4.13 \mathrm{E}-07$ | 3.00 | $9.09 \mathrm{E}-07$ | 3.00 | $1.45 \mathrm{E}-06$ | 3.00 | $2.75 \mathrm{E}-05$ | 2.07 |
| $P^{2}$ | 20 | $1.24 \mathrm{E}-05$ | - | $1.37 \mathrm{E}-05$ | - | $1.38 \mathrm{E}-04$ | - | $6.27 \mathrm{E}-04$ | - |
|  | 40 | $4.51 \mathrm{E}-07$ | 4.79 | $4.98 \mathrm{E}-07$ | 4.79 | $8.12 \mathrm{E}-06$ | 4.08 | $6.18 \mathrm{E}-05$ | 3.34 |
|  | 80 | $1.49 \mathrm{E}-08$ | 4.92 | $1.64 \mathrm{E}-08$ | 4.92 | $4.89 \mathrm{E}-07$ | 4.05 | $6.59 \mathrm{E}-06$ | 3.23 |
|  | 160 | $4.77 \mathrm{E}-10$ | 4.97 | $5.26 \mathrm{E}-10$ | 4.97 | $2.99 \mathrm{E}-08$ | 4.03 | $7.57 \mathrm{E}-07$ | 3.12 |
| $P^{3}$ | 30 | $3.70 \mathrm{E}-09$ | - | $4.98 \mathrm{E}-09$ | - | $4.52 \mathrm{E}-07$ | - | $9.72 \mathrm{E}-06$ | - |
|  | 40 | $5.07 \mathrm{E}-10$ | 6.91 | $6.77 \mathrm{E}-10$ | 6.93 | $1.07 \mathrm{E}-07$ | 5.02 | $3.23 \mathrm{E}-06$ | 3.84 |
|  | 50 | $1.06 \mathrm{E}-10$ | 6.99 | $1.42 \mathrm{E}-10$ | 6.99 | $3.48 \mathrm{E}-08$ | 5.01 | $1.31 \mathrm{E}-06$ | 4.04 |
|  | 60 | $2.97 \mathrm{E}-11$ | 7.01 | $3.96 \mathrm{E}-11$ | 7.01 | $1.39 \mathrm{E}-08$ | 5.02 | $6.15 \mathrm{E}-07$ | 4.15 |

Example 6.3 To illustrate the case with different boundary conditions and long time behaviors, consider the following problem

$$
\begin{array}{ll}
u_{t}+\left(u^{2} / 2\right)_{x}-b u_{x x}=g(x, t), & (x, t) \in[0,1] \times(0, T], \\
u(x, 0)=\cos (\pi(x-1) / 2)-\frac{e^{(x-1) / b}-1}{1-e^{-1 / b}}, & x \in[0,1]
\end{array}
$$

with mixed boundary conditions

Table 5 Errors and rates for Example 6.2 with $b=0.1, b=2.0, T=1$

|  | $N$ | $b=0.1$ |  |  |  | $b=2.0$ |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | $\left\\|\xi_{u}\right\\|$ | Rate | $\left\\|P_{h}^{-} u-u_{h}\right\\|$ | Rate | $\left\\|\xi_{u}\right\\|$ | Rate | $\left\\|P_{h}^{-} u-u_{h}\right\\|$ | Rate |
| $P^{1}$ | 40 | $7.68 \mathrm{E}-03$ | - | $1.16 \mathrm{E}-02$ | - | 2.84E-04 | - | $4.98 \mathrm{E}-04$ |  |
|  | 80 | $9.69 \mathrm{E}-04$ | 2.99 | $1.52 \mathrm{E}-03$ | 2.93 | $3.68 \mathrm{E}-05$ | 2.95 | $6.32 \mathrm{E}-05$ | 2.98 |
|  | 160 | $1.21 \mathrm{E}-04$ | 3.01 | $1.93 \mathrm{E}-04$ | 2.97 | $4.64 \mathrm{E}-06$ | 2.99 | $7.92 \mathrm{E}-06$ | 2.99 |
|  | 320 | $1.50 \mathrm{E}-05$ | 3.01 | $2.43 \mathrm{E}-05$ | 2.99 | $5.82 \mathrm{E}-07$ | 3.00 | $9.91 \mathrm{E}-07$ | 3.00 |
| $P^{2}$ | 20 | $1.53 \mathrm{E}-03$ | - | $1.98 \mathrm{E}-03$ | - | $1.82 \mathrm{E}-05$ | - | $1.17 \mathrm{E}-04$ | - |
|  | 40 | $3.03 \mathrm{E}-05$ | 5.66 | $1.18 \mathrm{E}-04$ | 4.07 | $6.32 \mathrm{E}-07$ | 4.85 | $7.26 \mathrm{E}-06$ | 4.01 |
|  | 80 | $7.50 \mathrm{E}-07$ | 5.33 | $7.23 \mathrm{E}-06$ | 4.03 | $2.04 \mathrm{E}-08$ | 4.95 | $4.52 \mathrm{E}-07$ | 4.01 |
|  | 160 | $2.13 \mathrm{E}-08$ | 5.13 | $4.47 \mathrm{E}-07$ | 4.02 | $6.48 \mathrm{E}-10$ | 4.98 | $2.82 \mathrm{E}-08$ | 4.00 |
| $P^{3}$ | 30 | $2.33 \mathrm{E}-06$ | - | $1.35 \mathrm{E}-05$ | - | $4.95 \mathrm{E}-09$ | - | $5.83 \mathrm{E}-07$ | - |
|  | 40 | $3.07 \mathrm{E}-07$ | 7.04 | $3.30 \mathrm{E}-06$ | 4.91 | $6.83 \mathrm{E}-10$ | 6.89 | $1.39 \mathrm{E}-07$ | 4.99 |
|  | 50 | $6.42 \mathrm{E}-08$ | 7.02 | $1.10 \mathrm{E}-06$ | 4.92 | $1.45 \mathrm{E}-10$ | 6.96 | $4.55 \mathrm{E}-08$ | 5.00 |
|  | 60 | $1.78 \mathrm{E}-08$ | 7.02 | $4.47 \mathrm{E}-07$ | 4.94 | $4.04 \mathrm{E}-11$ | 6.99 | $1.83 \mathrm{E}-08$ | 5.00 |

Table 6 Errors and rates for Example 6.2 with generalized fluxes for $b=2.0, T=1$

|  | $N$ | $\left\\|e_{u n}\right\\|$ | Rate | $\left\\|e_{u}\right\\|_{c}$ | Rate | $\left\\|e_{u r}\right\\|$ | Rate | $\left\\|e_{u r}^{\star}\right\\|$ | Rate |
| :--- | ---: | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
|  | 40 | $6.22 \mathrm{E}-05$ | - | $1.01 \mathrm{E}-04$ | - | $2.90 \mathrm{E}-04$ | - | $3.00 \mathrm{E}-03$ | - |
| $P^{1}$ | 80 | $7.52 \mathrm{E}-06$ | 3.05 | $1.19 \mathrm{E}-05$ | 3.08 | $3.45 \mathrm{E}-05$ | 3.07 | $7.15 \mathrm{E}-04$ | 2.07 |
| $\theta=1.5$ | 160 | $9.32 \mathrm{E}-07$ | 3.01 | $1.47 \mathrm{E}-06$ | 3.02 | $4.25 \mathrm{E}-06$ | 3.02 | $1.77 \mathrm{E}-04$ | 2.02 |
|  | 320 | $1.16 \mathrm{E}-07$ | 3.00 | $1.82 \mathrm{E}-07$ | 3.01 | $5.29 \mathrm{E}-07$ | 3.01 | $4.41 \mathrm{E}-05$ | 2.00 |
|  | 20 | $6.89 \mathrm{E}-06$ | - | $6.95 \mathrm{E}-06$ | - | $1.40 \mathrm{E}-04$ | - | $2.28 \mathrm{E}-03$ | - |
| $P^{2}$ | 40 | $1.71 \mathrm{E}-07$ | 5.33 | $1.72 \mathrm{E}-07$ | 5.34 | $8.42 \mathrm{E}-06$ | 4.06 | $2.70 \mathrm{E}-04$ | 3.07 |
| $\theta=0.8$ | 80 | $5.03 \mathrm{E}-09$ | 5.08 | $5.06 \mathrm{E}-09$ | 5.08 | $5.18 \mathrm{E}-07$ | 4.02 | $3.32 \mathrm{E}-05$ | 3.02 |
|  | 160 | $1.56 \mathrm{E}-10$ | 5.01 | $1.57 \mathrm{E}-10$ | 5.01 | $3.22 \mathrm{E}-08$ | 4.01 | $4.13 \mathrm{E}-06$ | 3.00 |
|  | 30 | $2.28 \mathrm{E}-09$ | - | $2.34 \mathrm{E}-09$ | - | $9.38 \mathrm{E}-07$ | - | $3.85 \mathrm{E}-05$ | - |
| $P^{3}$ | 40 | $2.94 \mathrm{E}-10$ | 7.13 | $3.01 \mathrm{E}-10$ | 7.13 | $2.31 \mathrm{E}-07$ | 4.86 | $1.26 \mathrm{E}-05$ | 3.86 |
| $\theta=1.2$ | 50 | $6.05 \mathrm{E}-11$ | 7.07 | $6.22 \mathrm{E}-11$ | 7.07 | $7.56 \mathrm{E}-08$ | 5.01 | $5.16 \mathrm{E}-06$ | 4.02 |
|  | 60 | $1.67 \mathrm{E}-11$ | 7.04 | $1.72 \mathrm{E}-11$ | 7.04 | $3.04 \mathrm{E}-08$ | 4.99 | $2.49 \mathrm{E}-06$ | 4.00 |

The source term $g(x, t)$ is specially chosen such that the exact solution is

$$
\begin{equation*}
u(x, t)=\left[\cos (\pi(x-1) / 2)-\frac{e^{(x-1) / b}-1}{1-e^{-1 / b}}\right] \cos (\pi t) \tag{6.1}
\end{equation*}
$$

When $b=100, T \neq 3$, the errors and their orders are presented in Table 7, from which we observe $(2 k+1)$ th order superconvergence for the cell averages and the numerical fluxes in the discrete $L^{2}$ norm. Superconvergence of order $k+2(k+1)$ can be seen for the function (derivative) value approximations and interior right (left) Radau points. This example indicates that the superconvergence results are also sharp when mixed boundary conditions are adopted.

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Table 7 Errors and rates for Example 6.3 with mixed boundary conditions, $b=100, T=3$

|  | $N$ | $\left\\|e_{\text {un }}\right\\|$ | Rate | $\left\\|e_{u}\right\\|_{c}$ | Rate | $\left\\|e_{u r}\right\\|$ | Rate | $\left\\|e_{u \ell}\right\\|$ | Rate |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| $P^{1}$ | 25 | $1.89 \mathrm{E}-08$ | - | $2.46 \mathrm{E}-06$ | - | $3.06 \mathrm{E}-06$ | - | $4.76 \mathrm{E}-06$ | - |
|  | 30 | $1.09 \mathrm{E}-08$ | 3.01 | $1.42 \mathrm{E}-06$ | 3.00 | $1.77 \mathrm{E}-06$ | 3.00 | $3.03 \mathrm{E}-06$ | 2.47 |
|  | 35 | $6.85 \mathrm{E}-09$ | 3.01 | $8.94 \mathrm{E}-07$ | 3.00 | $1.12 \mathrm{E}-06$ | 3.00 | $2.08 \mathrm{E}-06$ | 2.43 |
|  | 40 | $4.58 \mathrm{E}-09$ | 3.01 | $5.99 \mathrm{E}-07$ | 3.00 | $7.48 \mathrm{E}-07$ | 3.00 | $1.51 \mathrm{E}-06$ | 2.39 |
| $P^{2}$ | 10 | $3.02 \mathrm{E}-11$ | - | $4.73 \mathrm{E}-11$ | - | $2.27 \mathrm{E}-07$ | - | $5.08 \mathrm{E}-07$ | - |
|  | 15 | $3.89 \mathrm{E}-12$ | 5.05 | $6.27 \mathrm{E}-12$ | 4.98 | $4.51 \mathrm{E}-08$ | 3.99 | $1.25 \mathrm{E}-07$ | 3.45 |
|  | 20 | $8.05 \mathrm{E}-13$ | 5.48 | $1.58 \mathrm{E}-12$ | 4.80 | $1.43 \mathrm{E}-08$ | 3.99 | $4.77 \mathrm{E}-08$ | 3.36 |
|  | 25 | $2.28 \mathrm{E}-13$ | 5.65 | $5.46 \mathrm{E}-13$ | 4.75 | $5.86 \mathrm{E}-09$ | 4.00 | $2.28 \mathrm{E}-08$ | 3.31 |

Table 8 Errors and rates for Example 6.3 with Dirichlet boundary conditions, $b=1.5, T=100$

|  | $N$ | $\left\\|e_{\text {un }}\right\\|$ | Rate | $\left\\|e_{u}\right\\|_{c}$ | Rate | $\left\\|e_{u r}\right\\|$ | Rate | $\left\\|e_{u \ell}\right\\|$ | Rate |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| $P^{1}$ | 25 | $4.58 \mathrm{E}-07$ | - | $3.12 \mathrm{E}-06$ | - | $3.35 \mathrm{E}-06$ | - | $1.74 \mathrm{E}-04$ | - |
|  | 30 | $2.65 \mathrm{E}-07$ | 3.00 | $1.81 \mathrm{E}-06$ | 3.00 | $1.94 \mathrm{E}-06$ | 2.99 | $1.17 \mathrm{E}-04$ | 2.18 |
|  | 35 | $1.67 \mathrm{E}-07$ | 3.00 | $1.14 \mathrm{E}-06$ | 3.00 | $1.23 \mathrm{E}-06$ | 2.99 | $8.38 \mathrm{E}-05$ | 2.16 |
|  | 40 | $1.12 \mathrm{E}-07$ | 3.00 | $7.63 \mathrm{E}-07$ | 3.00 | $8.22 \mathrm{E}-07$ | 2.99 | $6.29 \mathrm{E}-05$ | 2.14 |
| $P^{2}$ | 10 | $1.74 \mathrm{E}-09$ | - | $5.32 \mathrm{E}-09$ | - | $3.89 \mathrm{E}-06$ | - | $1.61 \mathrm{E}-04$ | - |
|  | 15 | $2.67 \mathrm{E}-10$ | 4.62 | $6.93 \mathrm{E}-10$ | 5.03 | $7.79 \mathrm{E}-07$ | 3.96 | $4.84 \mathrm{E}-05$ | 2.96 |
|  | 20 | $7.48 \mathrm{E}-11$ | 4.42 | $1.59 \mathrm{E}-10$ | 5.11 | $2.48 \mathrm{E}-07$ | 3.98 | $2.06 \mathrm{E}-05$ | 2.97 |
|  | 25 | $2.50 \mathrm{E}-11$ | 4.92 | $5.77 \mathrm{E}-11$ | 4.55 | $1.02 \mathrm{E}-07$ | 3.98 | $1.06 \mathrm{E}-05$ | 2.98 |

To verify superconvergence results for Dirichlet boundary conditions with long time simulations, we consider Example 6.3 with the following Dirichlet boundary conditions

$$
u(0, t)=\cos (\pi t), \quad u(1, t)=\cos (\pi t)
$$

When $b=1.5, T=100$, the results with $\kappa=3.5 / h$ in numerical fluxes (5.4) are shown in Table 8, demonstrating that the conclusions still hold for Dirichlet boundary conditions and long time simulations.

Example 6.4 To illustrate the time-dependent singularly perturbed problems with a stationary outflow boundary layer, we would like to consider a nonlinear problem

$$
u_{t}+\left(e^{u}\right)_{x}-b u_{x x}=g(x, t), \quad(x, t) \in[0,1] \times(0, T],
$$

with Dirichlet boundary conditions and the same exact solution as (6.1). The initial solution and the source term $g(x, t)$ is determined by this exact solution. Note that when we take $b=10^{-5}$, the solution (6.1) varies quickly with a large gradient and forms an outflow boundary layer near the outflow boundary point $x=1$. When the Gauss-Radau projection $P_{h}^{-} u$ is used as the initial condition, we observe errors and the corresponding superconvergent rates in the local region [13]

$$
\left(0, x_{c}\right)=(0,1-\lceil\ln N\rceil h),
$$

where $\lceil\ln N\rceil$ denotes the minimal integer no less than $\ln N$. The results with $\kappa=2 / h$ in numerical fluxes (5.4) are shown in Table 9, from which we can see superconvergence

Table 9 Local errors and rates for Example 6.4 with Dirichlet boundary conditions, $b=10^{-5}, T=2$

|  | $N$ | $\left\\|e_{u n}\right\\|$ | Rate | $\left\\|e_{u}\right\\|_{c}$ | Rate | $\left\\|e_{u r}\right\\|$ | Rate | $\left\\|e_{u \ell}\right\\|$ | Rate |
| :--- | ---: | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| $P^{1}$ | 20 | $5.75 \mathrm{E}-07$ | - | $1.96 \mathrm{E}-06$ | - | $6.32 \mathrm{E}-06$ | - | $3.51 \mathrm{E}-04$ | - |
|  | 40 | $7.20 \mathrm{E}-08$ | 3.00 | $2.45 \mathrm{E}-07$ | 3.00 | $7.90 \mathrm{E}-07$ | 3.00 | $8.75 \mathrm{E}-05$ | 2.00 |
|  | 80 | $9.24 \mathrm{E}-09$ | 2.96 | $3.06 \mathrm{E}-08$ | 3.00 | $9.86 \mathrm{E}-08$ | 3.00 | $2.18 \mathrm{E}-05$ | 2.00 |
|  | 160 | $1.18 \mathrm{E}-09$ | 2.96 | $3.82 \mathrm{E}-09$ | 3.00 | $1.23 \mathrm{E}-08$ | 3.00 | $5.45 \mathrm{E}-06$ | 2.00 |
| $P^{2}$ | 20 | $1.76 \mathrm{E}-09$ | - | $2.71 \mathrm{E}-10$ | - | $5.52 \mathrm{E}-08$ | - | $4.45 \mathrm{E}-06$ | - |
|  | 40 | $1.74 \mathrm{E}-11$ | 6.66 | $7.63 \mathrm{E}-12$ | 5.15 | $3.53 \mathrm{E}-09$ | 3.97 | $5.75 \mathrm{E}-07$ | 2.95 |
|  | 60 | $2.34 \mathrm{E}-12$ | 4.94 | $1.35 \mathrm{E}-12$ | 4.27 | $7.00 \mathrm{E}-10$ | 3.99 | $1.72 \mathrm{E}-07$ | 2.97 |
|  | 80 | $3.29 \mathrm{E}-13$ | 6.82 | $2.78 \mathrm{E}-13$ | 5.48 | $2.22 \mathrm{E}-10$ | 3.99 | $7.31 \mathrm{E}-08$ | 2.98 |

property similar to the nonlinear hyperbolic equations [4] in the local region $\left(0, x_{c}\right)$. This is, both the cell averages error and numerical flux in the discrete $L^{2}$ norm converge at a rate of $2 k+1$, and the LDG error (its derivative) is superconvergent at interior right (left) Radau points with an order of $k+2(k+1)$.

## 7 Concluding Remarks

In this paper, we investigate superconvergence of the LDG method for one-dimensional nonlinear convection-diffusion equations. The main techniques are the construction of new projections and correction functions, allowing us to derive a supercloseness result between the LDG solution and an interpolation function. We have established $(2 k+1)$ th order superconvergence for the numerical flux and cell averages, as well as superconvergence at Radau points, even when the flow direction changes. The results are extended to generalized alternating fluxes and mixed boundary conditions. The sharpness of the theoretical results is verified by numerical experiments.

In further work, we will consider the degenerate nonlinear diffusion problems and multidimensional diffusion equations.

## Declarations

Conflict of Interest On behalf of all authors, the corresponding author states that there is no conflict of interest.

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